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DEPTH IMAGING AND APPLICATION IN POTATO QUALITY GRADING Qinghua Su,2023-11-25 As one of the world s most important crops potatoes play an important role in maintaining the stability of the global food supply Many countries including China believe that food supply security is a basic condition for maintaining national stability and development Therefore potatoes can not only solve the problem of international food shortage but also promote the development of international trade In recent years with the continuous improvement of planting technology the global production and trade volume of potatoes have also been continuously increasing However the development of traditional potato quality grading technology is relatively slow Currently it still relies on manual sorting in many countries and regions Because workers can not keep their attention for a long time under huge work pressure and their understanding of grading standards is inconsistent large amount of wrong potato grading often occurs This result not only affects farmers income but also causes serious waste in the potato processing due to unqualified raw potatoes In addition with the continuous increase of manual wages the cost of manual grading of potatoes has under challenge Therefore achieving automation of potato quality grading is imperative Traditional grading system mainly uses cameras to capture potato color images and achieves potato quality grading through color information analysis This method can reach high success rate for certain defects detection such as green skin surface rot and mechanical damage Due to the variety of shapes of potatoes growing underground the appearance defects such as bending bump and hollow are widely existing These abnormal samples may fail to be detected and grade to wrong quality groups the 3D appearance information cannot be fully perceived in 2D color images In response to such issues we have decided to build a machine vision system based on depth cameras which can obtain depth images of potatoes with 3D shape information Unlike each pixel in a color image that stores color information each pixel in a depth image stores the distance from the target to the camera Therefore

the potato 3D surface features can be sensed and used for bump and hollow defects detection To capture high quality depth images we have constructed a specialized depth imaging system and developed the image acquisition software based on OpenCV and OpenNI framework Then each potato surface features are analyzed and extracted for shape analysis defect detection and overall quality grading In recent years machine learning technology has developed rapidly and has been widely applied in fields such as object recognition and feature detection Hence we also apply machine learning technology to the field of potato quality grading By developing a machine learning model based on convolutional neural networks we can directly input potato depth images and get the corresponding quality level of the samples The experiment achieved good grading results Since color and depth images of potatoes are actually collected simultaneously in data collection step a novel algorithm is developed for potato 3D model rebuilding The method is based on Point Cloud Library and OpenGL technology and it shows the advantage in solving the problem of data traceability especially when users have objections to automatic quality classification results This model not only displays 3D potato shape model but also supports scaling and 360 degree rotation operations Overall we believe that with the development of machine learning and depth sensing potato quality grading systems will become more intelligent efficient and low cost

Proceedings of the 19'th Annual Tcl Association Tcl/Tk conference Tcl Association Press,2012-12-31 Conference proceedings of the U S Tcl conference of 2012 Electrodynamic and Mechatronic Systems Bronisław Tomczuk,Andrzej Waindok,Jan Zimon,2014-02-27 Selected peer reviewed extended papers from the International Symposium on Electrodynamic and Mechatronic Systems SELM 2013 May 15 18 2013

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