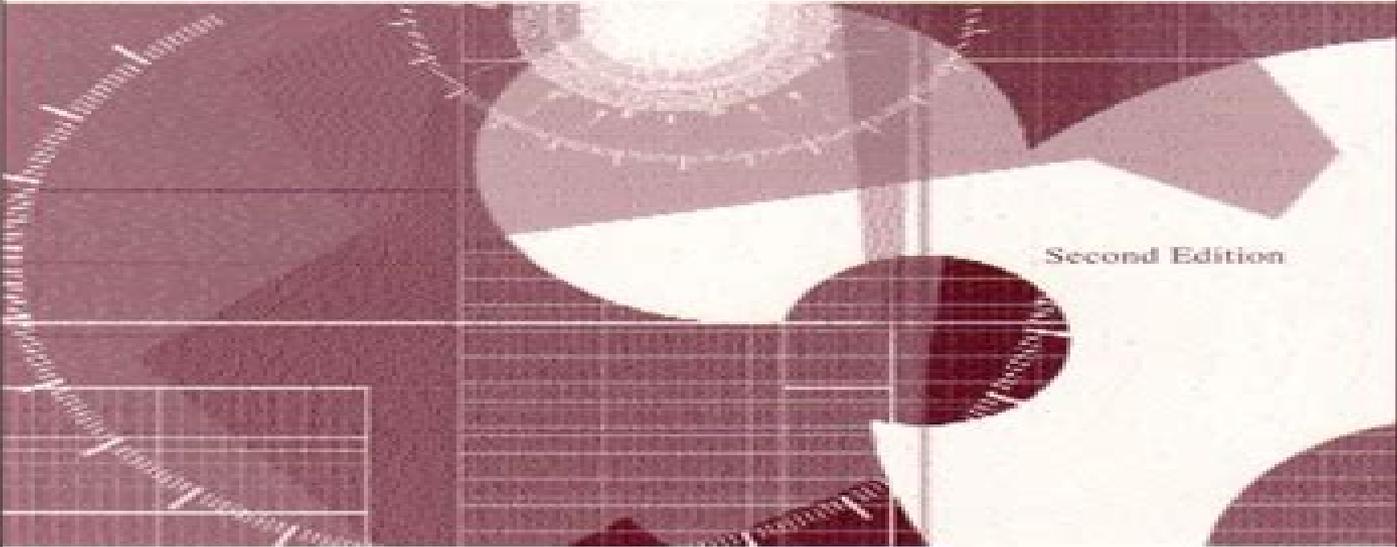


Laboratory Exercises

to accompany

Introduction to
MECHATRONICS
and Measurement Systems

Second Edition



David G. Alciatore  Michael B. Hstand

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multitude of disciplines technologies and their interaction whereas the science of mechatronics concerns the invention and development of new theories models concepts and tools in response to new needs evolving from interacting scientific disciplines The book includes two sections the first section includes chapters introducing research advances in mechatronics engineering and the second section includes chapters that reflects the teaching approaches theoretical projects and laboratories and curriculum development for under and postgraduate studies Mechatronics engineering education focuses on producing engineers who can work in a high technology environment emphasize real world hands on experience and engage in challenging problems and complex tasks with initiative innovation and enthusiasm Contents 1 Interdisciplinary Mechatronics Engineering Science and the Evolution of Human Friendly and Adaptive Mechatronics Maki K Habib 2 Micro Nanomechatronics for Biological Cell Analysis and Assembly Toshio Fukuda Masahiro Nakajima Masaru Takeuchi Tao Yue and Hirotaka Tajima 3 Biologically Inspired CPG Based Locomotion Control System of a Biped Robot Using Nonlinear Oscillators with Phase Resetting Shinya Aoi 4 Modeling a Human s Learning Processes toward Continuous Learning Support System Tomohiro Yamaguchi Kouki Takemori and Keiki Takadama 5 PWM Waveform Generation Using Pulse Type Hardware Neural Networks Ken Saito Minami Takato Yoshifumi Sekine and Fumio Uchikoba 6 Parallel Wrists Limb Types Singularities and New Perspectives Raffaele Di Gregorio 7 A Robot Assisted Rehabilitation System RehabRoby Duygun Erol Barkana and Fatih zkul 8 MIMO Actuator Force Control of a Parallel Robot for Ankle Rehabilitation Andrew Mcdaid Yun Ho Tsoi and Shengquan Xie 9 Performance Evaluation of a Probe Climber for Maintaining Wire Rope Akihisa Tabata Emiko Hara and Yoshio Aoki 10 Fundamentals on the Use of Shape Memory Alloys in Soft Robotics Matteo Cianchetti 11 Tuned Modified Transpose Jacobian Control of Robotic Systems S A A Moosavian and M Karimi 12 Derivative Free Nonlinear Kalman Filtering for PMSG Sensorless Control Gerasimos Rigatos Pierluigi Siano and Nikolaos Zervos 13 Construction and Control of Parallel Robots Moharam Habibnejad Korayem Soleiman Manteghi and Hami Tourajizadeh 14 A Localization System for Mobile Robot Using Scanning Laser and Ultrasonic Measurement Kai Liu Hongbo Li and Zengqi Sun 15 Building of Open Structure Wheel Based Mobile Robotic Platform Aleksandar Rodic and Ivan Stojkovic 16 Design and Physical Implementation of Holonomous Mobile Robot Holbos Jasmin Velagic Admir Kaknjo Faruk Dautovic Muhidin Hujdur and Nedim Osmic 17 Advanced Artificial Vision and Mobile Devices for New Applications in Learning Entertainment and Cultural Heritage Domains Gian Luca Foresti Niki Martinel Christian Micheloni and Marco Vernier 18 Application of Stereo Vision and ARM Processor for Motion Control Moharam Habibnejad Korayem Michal Irani and Saeed Rafee Nekoo 19 Mechatronics as Science and Engineering or Both Balan Pillai and Vesa Salminen 20 A Mechatronic Platform for Robotic Educational Activities Ioannis Kostavelis Evangelos Boukas Lazaros Nalpantidis and Antonios Gasteratos 21 The Importance of Practical Activities in the Formation of Mechatronic Engineers Joao Carlos M Carvalho and Vera L cia D S Franco About the Authors Maki K Habib is Professor of Robotics and Mechatronics in the School of Science and Engineering at the American University

in Cairo Egypt He has been regional editor Africa Middle East for the International Journal of Mechatronics and Manufacturing Systems IJMMS since 2010 He is the recipient of academic awards and has published many articles and books

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Introduction to Mechatronics Laboratory Excercises David G. Alciatore,Michael B. Histan,2003-05-01 Provides students and professionals with a resource for project and lab work for electromechanical systems The 15 experiments included in this work cover a range of subjects from basic instrumentation and measurement to use of microcontrollers and accelerometers It includes a general equipment list [International Workshop on Electronic Design, Test and Applications](#) Michel Renovell,2002 A collection of the 78 oral presentations and 24 poster papers from the January 2002 international workshop which brought together specialists from a broad area of electronic design manufacturing test and advanced system applications in the hope that the conference would integrate design test and application as cross dependent disciplines The contributions are organized into sessions focusing on analog test communications digital signal processing and architectures low to high level fault simulation and identification high level design memory power issues in design and test sensor and analog design electrical engineering education electromagnetics and control fault tolerant digital systems image processing

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