```python
import numpy as np #importing math function library
import matplotlib.pyplot as plt #importing graphical library
from decimal import getcontext, Decimal
import scipy
import CtetEoM as CT

old_settings = np.seterr(all = 'ignore')

getcontext().prec = 5 #setting decimal allowance

t = np.linspace(0, 1000.0, 1000) #  timestep vector with timestep t[1] - t[0]

I = [np.array([1, 2.0125, 0.035, 0.1]),\
            np.array([2.3, 5.3, 0.3, 0.1]),\
            np.array([2.35, 1.071, 0.04, 0.35]),\
            np.array([1.03, 5.01, 0.01, 0.2])\
            ] #array of various inital vectors


def m(vpair, tpair): #defining the equations of motion

    (A1, A2, P1, P2) = tuple(vpair) #forms iterable item from the array vpair

    return np.array([CT.DA1(A1, A2, P1, P2), CT.DA2(A1, A2, P1, P2), CT.DP1(A1, A2, P1, P2), CT.DP2(A1, A2, P1, P2)]).T


def rk4(f, t, y0): #defining runge kutta function for multiple coupled equations with intial conditions
                #        v0and time step vector t
    N = len(t)

    y = np.array([k*np.ones(N) for k in y0]).T # N by length(v0) array to store iterations,
        #                                              takes transpose
    for ii in range(N-1):

        h = t[ii+1] - t[ii] #
        k1 = h * f(y[ii], t[ii])
        k2 = h * f(y[ii] + 0.5 * k1, t[ii] + 0.5 * h)
        k3 = h * f(y[ii] + 0.5 * k2, t[ii] + 0.5 * h)
```

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M Carnoy

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