

1.2 Industrial robots - definition and classification

1.2.1 Definition (ISO 8373:2012) and delimitation

The annual surveys carried out by IFR focus on the collection of yearly statistics on the production, imports, exports and domestic installations/shipments of **industrial robots (at least three or more axes)** as described in the ISO definition given below. Figures 1.1 shows examples of robot types which are covered by this definition and hence included in the surveys.

A robot which has its own control system and is not controlled by the machine should be included in the statistics, although it may be dedicated for a special machine. Other dedicated industrial robots should not be included in the statistics. If countries declare that they included dedicated industrial robots, or are suspected of doing so, this will be clearly indicated in the statistical tables. It will imply that data for those countries is not directly comparable with those of countries that strictly adhere to the definition of multipurpose industrial robots.

- Wafer handlers have their own control system and should be included in the statistics of industrial robots. Wafers handlers can be articulated, cartesian, cylindrical or SCARA robots. Irrespective from the type of robots they are reported in the application "cleanroom for semiconductors".
- Flat panel handlers also should be included. Mainly they are articulated robots. Irrespective from the type of robots they are reported in the application "cleanroom for FPD".

Examples of dedicated industrial robots that should not be included in the international survey are:

- Equipment dedicated for loading/unloading of machine tools (see figure 1.3).
- Dedicated assembly equipment, e.g. for assembly on printed circuit boards (see figure 1.3).
- Integrated Circuit Handlers (pick and place)
- Automated storage and retrieval systems (see figure 1.3).
- Automated guided vehicles (AGVs) (see "World Robotics Service Robots")

The submission of statistics on industrial robots is mandatory for IFR member associations. In some countries, however, data is also collected on all types of manipulating industrial robots, that is, both multipurpose and dedicated manipulating industrial robots. Optionally, national robot associations may therefore also submit statistics on all types of manipulating industrial robots, which will be included in the publication *World Robotics* under the respective country chapter.

Industrial robot as defined by ISO 8373:2012:

An automatically controlled, reprogrammable, multipurpose manipulator programmable in three or more axes, which can be either fixed in place or mobile for use in industrial automation applications

The terms used in the definition above are explained in more detail below:

- **Reprogrammable:** designed so that the programmed motions or auxiliary functions can be changed without physical alteration;

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An Overview of Artificial Intelligence and Robotics William B. Gevarter,1982 **Proceedings of Symposium for International Co-operation on Industrial Robots '87** ,1987 An Overview of Artificial Intelligence and Robotics. Volume II - Robotics William B. Gevarter,United States. National Bureau of Standards,1982 Industrial Robotics Harry Colestock,2005 This detailed reference shows how to achieve maximum productivity with robotics classifies robots according to their complexity and function and explains how to avoid common automation mistakes **Production and Use of Industrial Robots: Trends in the manufacture and use of industrial robots** ,1983 13th International Symposium on Industrial Robots and Robots 7: Future directions ,1983 Theory and Practice of Robots and Manipulators International Centre for Mechanical Sciences,1977 Robotics and Industrial Engineering Edward L. Fisher,1983 **Industrial Robots Industry in Japan** Yano Economic Research Institute,1981 JEE, Journal of Electronic Engineering ,1982 **Industrial Robots** P. Lammineur,O. Cornillie,1984 **Science & Technology in Japan** ,1982 Decade of Robotics John Mortimer,1983 Marking the 10th anniversary of Industrial Robotics magazine Contains over 40 articles specially written by experts in robotics worldwide **Handbook of Industrial Robotics** Shimon Y. Nof,1992 120 leading experts from twelve countries have participated in creating this Second Edition of the Handbook of Industrial Robotics Of its 66 chapters 33 are new covering important new topics in the theory design control and applications of robotics Other key features include a larger glossary of robotics terminology with over 800 terms and a CD ROM that vividly conveys the colorful motions and intelligence of robotics With contributions from the most prominent names in robotics worldwide the Handbook remains the essential resource on all aspects of this complex subject

Decoding **1 2 Industrial Robots Definition And Classification**: Revealing the Captivating Potential of Verbal Expression

In a time characterized by interconnectedness and an insatiable thirst for knowledge, the captivating potential of verbal expression has emerged as a formidable force. Its power to evoke sentiments, stimulate introspection, and incite profound transformations is genuinely awe-inspiring. Within the pages of "**1 2 Industrial Robots Definition And Classification**," a mesmerizing literary creation penned with a celebrated wordsmith, readers embark on an enlightening odyssey, unraveling the intricate significance of language and its enduring effect on our lives. In this appraisal, we shall explore the book's central themes, evaluate its distinctive writing style, and gauge its pervasive influence on the hearts and minds of its readership.

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