



## IBM Integration Bus V10 Application Development I

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<b>Code:</b>	WM666G
<b>Length:</b>	5 days
<b>URL:</b>	<a href="#">View Online</a>

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This course is also available as self-paced virtual (e-learning) course *IBM Integration Bus V10 Application Development I* (ZM666G). This option does not require any travel.

IBM Integration Bus provides connectivity and universal data transformation in heterogeneous IT environments. It enables businesses of any size to eliminate point-to-point connections and batch processing, regardless of operating system, protocol, and data format.

This course teaches you how to use IBM Integration Bus to develop, deploy, and support message flow applications. These applications use various messaging topologies to transport messages between service requesters and service providers, and also allow the messages to be routed, transformed, and enriched during processing.

In this course, you learn how to construct applications to transport and transform data. The course also explores how to control the flow of data by using various processing nodes, and how to use databases and maps to transform and enrich data during processing. You also learn how to construct data models by using the Data Format Description Language (DFDL).

### Skills Gained

Describe the features and uses of the IBM Integration Bus.

Develop, deploy, and test message flow applications.

Generate message flow applications from predefined patterns.

Use IBM Integration Bus problem determination aids to diagnose and solve development and runtime errors.

Describe the function and appropriate use of IBM Integration Bus processing nodes.

Write basic Extended Structured Query Language and Java programs to transform data.

Use the IBM Graphical Data Mapping editor to transform data.

Define, use, and test simple XML and Data Format Description Language (DFDL) data models.

Describe supported transport protocols and how to call them in message flows.

# Ibm Integration Bus V10 Application Development I

**David Baud**



## **Ibm Integration Bus V10 Application Development I:**

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web if one has a linear transformation in functional form it is easy to determine the transformation matrix a by transforming

each of the vectors of the standard basis by  $t$  then inserting the result into the columns of a matrix in other words for example the function is a linear transformation

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web in linear algebra a rotation matrix is a transformation matrix that is used to perform a rotation in euclidean space for example using the convention below the matrix rotates points in the  $xy$  plane counterclockwise through an angle  $\theta$  about the origin of a two dimensional cartesian coordinate system

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web orthogonality of the transformation matrix  $Q$  as in the two dimensional case the transformation matrix is orthogonal  $Q^T Q = I$  this follows from 1 5 11 1 5 13 example consider a cartesian coordinate system with base vectors  $e_i$  a coordinate transformation is carried out with the new basis given by  $\begin{pmatrix} 3 & 3 & 2 \\ 3 & 3 & 1 \\ 2 & 3 & 3 \\ 1 & 3 & 2 \end{pmatrix}$

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web coordinates of  $v$  the standard coordinates are  $v_3$  are the  $b_1$   $b_2$  are assumed if no other basis is specified this means  $v_3 = e_1 + e_2 + e_3$  if  $b_1, b_2, b_3$  is a basis of  $\mathbb{R}^3$  then the matrix  $S$  which contains the vectors  $v_k$  as column vectors is called the coordinate change matrix

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web the vector  $b$  is parallel to  $a$  and points in the same direction if  $\alpha > 0$  for  $\alpha < 0$  the vector  $b$  is parallel to but points in the opposite direction antiparallel if we multiply an arbitrary vector  $a$  by the inverse of its magnitude  $1/|a|$  we obtain a

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web and now that we know what  $D$  is we can now solve for  $A$  we can now solve for the transformation matrix with respect to the standard basis so to do that we have to figure out  $C$  and  $C^{-1}$  so  $C$  remember  $C$  is just the change of basis matrix and all that is is the basis vectors it's just a matrix with the basis vectors in the column

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web a translation by a nonzero vector is not a linear map because linear maps must send the zero vector to the zero vector however translations are very useful in performing coordinate transformations i'll introduce the following terminology for the composite of a linear transformation and a translation definition let  $A$  be a real matrix

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web any vector  $v$  represented in  $b$  can be transformed to a representation in  $c$  as follows under the transformation of basis notice that the superscript on the transformation matrix  $m$  and the subscript on the coordinate vector  $v$  are the same and seemingly cancel leaving the remaining subscript

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