

# Nine-Axis Sensor Fusion Using the Direction Cosine Matrix Algorithm on the MSP430F5xx Family

Erik Anders, Gabriel Torres, Sushruth Ravindran

## ABSTRACT

This application report explains the implementation of an Attitude and Heading Reference System (AHRS), using the ultra-low-power MSP430F5xx microcontroller, a magnetometer, a gyroscope, and an accelerometer on all three axes. The combination of the sensors is key to the accuracy of the algorithm. Therefore, the sensors' output must be calibrated before being input to the Direction Cosine Matrix (DCM) algorithm. The algorithm is applied to the calibrated sensor readings to calculate the Euler angles describing the orientation of a body, consisting of the yaw, roll, and pitch angles.

Project collateral and source code discussed in this application report can be downloaded from the following URL: <http://www.ti.com/MS430AHRS>.

This application report uses the MPLAB® IDE Microchip™ Windows Developer Kit from Interphase (<http://www.interphase.com>).

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# Nine Axis Sensor Fusion Using Direction Cosine Matrix

**Hussin A.Rothana**



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Sensor Fusion Approaches for Positioning, Navigation, and Mapping Mohamed M. Atia, 2025-01-22 Unique exploration of the integration of multi sensor approaches in navigation and positioning technologies Sensor Fusion Approaches for Positioning Navigation and Mapping discusses the fundamental concepts and practical implementation of sensor fusion in positioning and mapping technology explaining the integration of inertial sensors radio positioning systems visual sensors depth sensors radar measurements and LiDAR measurements The book includes case studies on ground wheeled vehicles drones and wearable devices to demonstrate the presented concepts To aid in reader comprehension and provide readers with hands on training in sensor fusion pedagogical features are included throughout the text block diagrams photographs plot graphs examples solved problems case studies sample codes with instruction manuals and guided tutorials Rather than simply addressing a specific sensor or problem domain without much focus on the big picture of sensor fusion and integration Sensor Fusion Approaches for Positioning Navigation and Mapping utilizes a holistic and comprehensive approach to enable readers to fully grasp interrelated concepts Written by a highly qualified author Sensor Fusion Approaches for Positioning Navigation and Mapping discusses sample topics such as Mathematical background covering linear algebra Euclidean space coordinate frames rotation and transformation quaternion and lie groups algebra Kinematics of rigid platforms in 3D space covering motion modeling in rotating and non rotating frames and under gravity field and different representations of position velocity and orientation Signals and systems covering measurements and noise probability concepts random processes signal processing linear dynamic systems and stochastic systems Theory measurements and signal processing of state of the art positioning and mapping sensors systems covering inertial sensors radio positioning systems ranging and detection sensors and imaging sensors State Estimation and Sensor Fusion methods covering filtering based methods and learning based approaches A comprehensive introductory text on the subject Sensor Fusion Approaches for Positioning Navigation and Mapping enables students to grasp the fundamentals of the subject and support their learning via ample pedagogical features Practicing robotics and navigation systems engineers can implement included sensor fusion algorithms on practical platforms

**Innovation, Engineering and Entrepreneurship** José Machado, Filomena Soares, Germano Veiga, 2018-06-02 This book presents endeavors to join synergies in order to create added value for society using the latest scientific knowledge to boost technology transfer from academia to industry It potentiates the foundations for the creation of knowledge and entrepreneurial cooperation networks involving engineering innovation and entrepreneurship stakeholders The Regional HELIX 2018 conference was organized at the University of Minho's School of Engineering by the METRICs and Algoritmi Research Centers and took place in Guimarães Portugal from June 27th to 29th 2018 After a rigorous peer review process 160 were accepted for publication covering a wide range of topics including Control Automation and Robotics Mechatronics Design Medical Devices and Wellbeing Cyber Physical

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**Field and Service Robotics** Alexander Zelinsky, 2012-12-06 Joe Engelberger the pioneer of the robotics industry wrote in his 1989 book *Robotics in Service* that the inspiration to write his book came as a reaction to an industry sponsored forecast study of robot applications which predicted that in 1995 applications of robotics outside factories the traditional domain of industrial robots would amount to less than 1% of total sales Engelberger believed that this forecast was very wrong and instead predicted that the non industrial class of robot applications would become the largest class Engelbergers prediction has yet to come to pass However he did correctly foresee the growth in non traditional applications of robots Robots are now beginning to march from the factories and into field and service applications This book presents a selection of papers from the first major international conference dedicated to field and service applications of robotics This selection includes papers from the leading research laboratories in the world together with papers from companies that are building and selling new and innovative robotic technology It describes interesting aspects of robots in the field ranging from mining agriculture construction cargo handling subsea operations removal of landmines to terrestrial exploration It also covers a diverse range of service applications such as cleaning propagating plants and aiding the elderly and handicapped and gives considerable attention to the technology required to realise robust reliable and safe robots

*Digital Avionics Handbook*  
Cary R. Spitzer, 2007 This 2 volume set includes new chapters on the time triggered protocol communications vehicle health management systems development guidelines and certification considerations and the Genesis platform It also discusses avionics building blocks and covers key development activities

**Sensor Fusion** , 1989-03

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