

# C Programming of Microcontrollers for Hobby Robotics

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**Abstract.** This handout supplies the necessary start up information for programming microcontrollers in C language. The examples of the handout is selected on the amateur robotics applications such as line tracking by a mobile platform, on-off, proportional, proportional-integral-derivative control for servomotor control.

**Keywords:** PIC microcontroller, C for hobby robotics, line tracking, PID controller.

## 1 Introduction

This article is written for the novice robotics hobbyists who want to have a quick start in microprocessor programming, for the IIRC 2008 Robotics Competition. It is a great opportunity for a hobbyist to enjoy the competition with a home-made robot.

A *microcontroller* (or MCU) [1] is a computer-on-a-chip used to control electronic devices. It is a type of microprocessor emphasizing self-sufficiency and cost-effectiveness, in contrast to a general-purpose microprocessor used in a PC. A typical microcontroller contains all the memory and interfaces needed for a simple application, whereas a general purpose microprocessor requires additional chips to provide the same functions.

The microcontroller applications are mainly categorized into the following fields in an alphabetic listing: Audio; Automotive; Wired communication; Computers and peripherals; Consumer Appliances; Industrial Instrumentation; Imaging and video application; Medical Instrumentation; Military and aerospace instrumentation; Mobile and wireless devices; Motor control; Security Equipments; General Purpose Devices; and Miscellaneous Applications. From these fields, robotics uses the wired and wireless communication, image processing, and motor control extensively.

A microcontroller is a must of a mechatronics device which combines intelligence, mechanical actions, and sensory devices for a goal. Robotics and Hobby Robotics are typical fields of mechatronics. In a robot, microcontrollers are embedded to implement intelligent control algorithms.

A low-end microcontroller can execute most of the robotics control algorithms. Implementation of robotics microcontroller applications requires two main components, a microcontroller and its IC-programming tool, and a convenient programming language to express the algorithms. The main objective of this article is an introduction to these item.

# C Programming Of Microcontrollers For Hobby Robotics

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## **Table of Contents C Programming Of Microcontrollers For Hobby Robotics**

1. Understanding the eBook C Programming Of Microcontrollers For Hobby Robotics
  - The Rise of Digital Reading C Programming Of Microcontrollers For Hobby Robotics
  - Advantages of eBooks Over Traditional Books
2. Identifying C Programming Of Microcontrollers For Hobby Robotics
  - Exploring Different Genres
  - Considering Fiction vs. Non-Fiction
  - Determining Your Reading Goals
3. Choosing the Right eBook Platform
  - Popular eBook Platforms
  - Features to Look for in an C Programming Of Microcontrollers For Hobby Robotics
  - User-Friendly Interface
4. Exploring eBook Recommendations from C Programming Of Microcontrollers For Hobby Robotics
  - Personalized Recommendations
  - C Programming Of Microcontrollers For Hobby Robotics User Reviews and Ratings
  - C Programming Of Microcontrollers For Hobby Robotics and Bestseller Lists
5. Accessing C Programming Of Microcontrollers For Hobby Robotics Free and Paid eBooks
  - C Programming Of Microcontrollers For Hobby Robotics Public Domain eBooks
  - C Programming Of Microcontrollers For Hobby Robotics eBook Subscription Services
  - C Programming Of Microcontrollers For Hobby Robotics Budget-Friendly Options
6. Navigating C Programming Of Microcontrollers For Hobby Robotics eBook Formats
  - ePub, PDF, MOBI, and More
  - C Programming Of Microcontrollers For Hobby Robotics Compatibility with Devices
  - C Programming Of Microcontrollers For Hobby Robotics Enhanced eBook Features
7. Enhancing Your Reading Experience
  - Adjustable Fonts and Text Sizes of C Programming Of Microcontrollers For Hobby Robotics
  - Highlighting and Note-Taking C Programming Of Microcontrollers For Hobby Robotics
  - Interactive Elements C Programming Of Microcontrollers For Hobby Robotics

8. Staying Engaged with C Programming Of Microcontrollers For Hobby Robotics
  - Joining Online Reading Communities
  - Participating in Virtual Book Clubs
  - Following Authors and Publishers C Programming Of Microcontrollers For Hobby Robotics
9. Balancing eBooks and Physical Books C Programming Of Microcontrollers For Hobby Robotics
  - Benefits of a Digital Library
  - Creating a Diverse Reading Collection C Programming Of Microcontrollers For Hobby Robotics
10. Overcoming Reading Challenges
  - Dealing with Digital Eye Strain
  - Minimizing Distractions
  - Managing Screen Time
11. Cultivating a Reading Routine C Programming Of Microcontrollers For Hobby Robotics
  - Setting Reading Goals C Programming Of Microcontrollers For Hobby Robotics
  - Carving Out Dedicated Reading Time
12. Sourcing Reliable Information of C Programming Of Microcontrollers For Hobby Robotics
  - Fact-Checking eBook Content of C Programming Of Microcontrollers For Hobby Robotics
  - Distinguishing Credible Sources
13. Promoting Lifelong Learning
  - Utilizing eBooks for Skill Development
  - Exploring Educational eBooks
14. Embracing eBook Trends
  - Integration of Multimedia Elements
  - Interactive and Gamified eBooks

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