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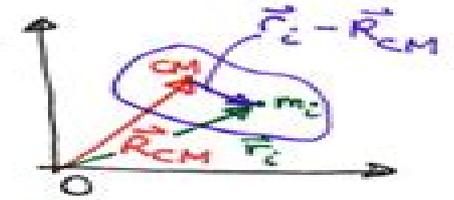
MH

K-H

10.6

3.8 Classical spin - angular momentum about the CM

For a system of masses (discrete or continuous) we can define total angular momentum w.r.t. O as



$$\vec{L}_O = \sum_i \vec{r}_i \times \vec{p}_i = \sum_i m_i (\vec{r}_i \times \vec{v}_i) \quad \vec{L}_O \text{ changes with } O!$$

$$\vec{R}_{CM} := \frac{1}{M} \sum_i m_i \vec{r}_i \quad , \quad \text{where } M = \sum_i m_i$$

now add to \vec{L}_O a zero $0 = \sum_i m_i (\vec{R}_{CM} \times \vec{v}_i) - \sum_i m_i (\vec{R}_{CM} \times \vec{v}_i)$

$$\vec{L}_O = \underbrace{\sum_i (\vec{r}_i - \vec{R}_{CM}) \times \vec{p}_i}_{\vec{L}_{tot} \text{ w.r.t. } \vec{R}_{CM}} + \underbrace{\sum_i \vec{R}_{CM} \times \vec{p}_i}_{= \vec{R}_{CM} \times \sum_i \vec{p}_i = \vec{R}_{CM} \times \vec{P}} = \vec{L}_{CM} + \vec{R}_{CM} \times \vec{P}$$

Angular momentum about O = angular momentum about CM + angular momentum of CM about O .

$\vec{L}_{CM} := \sum_i (\vec{r}_i - \vec{R}_{CM}) \times \vec{p}_i$ is the intrinsic angular momentum or classical spin of the body.

No external torques on CM $\Rightarrow \frac{d}{dt} \vec{L}_{CM} = 0$

or: $\frac{d}{dt} \vec{L}_{CM} = \vec{N}_{CM}^{ext}$

The CM provides a natural reference system for calculating angular momentum and torque in an N-body object.

Application: Earth's rotation axis points currently towards the North star (polar star). This axis, however, sweeps out a cone with 23.5° opening angle, and period 25,800 years. Implication: External forces generate a precession.

Assignment Classical Mechanics Solution

Yasmina Bestaoui Sebbane



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Encyclopaedia of Mathematics Michiel Hazewinkel,2012-12-06 This is the first Supplementary volume to Kluwer s highly acclaimed *Encyclopaedia of Mathematics* This additional volume contains nearly 600 new entries written by experts and covers developments and topics not included in the already published 10 volume set These entries have been arranged alphabetically throughout A detailed index is included in the book This Supplementary volume enhances the existing 10 volume set Together these eleven volumes represent the most authoritative comprehensive up to date *Encyclopaedia of Mathematics* available

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described in relation to computational chemistry such as molecular modeling and MD simulation toward close collaboration of SFG spectroscopy and computational chemistry in the near future

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Solved Problems in Classical Mechanics O. L. de Lange, J. Pierrus, 2010-05-06 Apart from an introductory chapter giving a brief summary of Newtonian and Lagrangian mechanics this book consists entirely of questions and solutions on topics in classical mechanics that will be encountered in undergraduate and graduate courses These include one two and three dimensional motion linear and nonlinear oscillations energy potentials momentum and angular momentum spherically symmetric potentials multi particle systems rigid bodies translation and rotation of the reference frame the relativity principle and some of its consequences The solutions are followed by a set of comments intended to stimulate inductive reasoning and provide additional information of interest Both analytical and numerical computer techniques are used to obtain and analyze solutions The computer calculations use Mathematica version 7 and the relevant code is given in the text It includes use of the interactive Manipulate function which enables one to observe simulated motion on a computer screen and to study the effects of changing parameters The book will be useful to students and lecturers in undergraduate and graduate courses on classical mechanics and students and lecturers in courses in computational physics

Classical Mechanics Carolina C. Ilie, Zachariah S. Schrecengost, Elina M. van Kempen, 2022-12-29 This book of problems and solutions in classical mechanics is dedicated to junior or senior undergraduate students in physics engineering applied mathematics astronomy or chemistry who may want to improve their problems solving skills or to freshman graduate students who may be seeking a refresh of the material The book is structured in ten chapters starting with Newton's laws motion with air resistance conservation laws oscillations and the Lagrangian and Hamiltonian Formalisms The last two chapters introduce some ideas in nonlinear dynamics chaos and special relativity Each chapter starts with a brief theoretical outline and continues with problems and detailed solutions A concise presentation of differential equations can be found in the appendix A variety of problems are presented from the standard classical mechanics problems to context rich problems and more challenging problems Key features Presents a theoretical outline for

each chapter Motivates the students with standard mechanics problems with step by step explanations Challenges the students with more complex problems with detailed solutions The Logical Analysis of Quantum Mechanics Erhard Scheibe,1973 *Proceedings of the Physical Society* Physical Society of London,1927 **Proceedings of the Physical Society** Institute of Physics and the Physical Society,1927 Proceedings American Society for Engineering Education. Conference,1985 **Collected Papers on Wave Mechanics** Erwin Schrödinger,1928 Solutions Manual to Accompany Classical Mechanics Tai L. Chow,1995 **On the S-states of the Two-electron Atom** Fred George Fender,1936
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