

PHYS 410 Homework # 8

6.1. On a spherical surface, the longitude and latitude lines are orthogonal.



For a small change in position, we have the change in longitude and latitude:

$$ds_{\phi} = R \cdot d\theta, \quad ds_{\lambda} = R \sin\theta \cdot d\phi$$

$$\Rightarrow ds = \sqrt{ds_{\phi}^2 + ds_{\lambda}^2} = R \cdot d\theta \sqrt{1 + \sin^2\theta \frac{d\phi^2}{d\theta^2}}$$

$$\Rightarrow L = \int_R ds = R \int_{\theta_1}^{\theta_2} \sqrt{1 + \sin^2\theta \frac{d\phi^2}{d\theta^2}} \cdot d\theta$$

6.3



$$L(P, Q) = \sqrt{x_1^2 + y_1^2 + z_1^2} + \sqrt{x_2^2 + y_2^2 + z_2^2}$$

$$\Rightarrow T = L/c$$

According to Fermat's principle, we get:

$$\frac{\delta T}{\delta x} = 0, \quad \frac{\delta T}{\delta y} = 0.$$

$$\frac{\delta T}{\delta x} = 0 \Rightarrow 2 \cdot \left(\frac{1}{\sqrt{x_1^2 + y_1^2 + z_1^2}} + \frac{1}{\sqrt{x_2^2 + y_2^2 + z_2^2}} \right) = 0 \Rightarrow z = 0 \quad (1)$$

$$\frac{\delta T}{\delta y} = 0 \Rightarrow \frac{y_1}{\sqrt{x_1^2 + y_1^2 + z_1^2}} + \frac{y_2}{\sqrt{x_2^2 + y_2^2 + z_2^2}} = 0 \quad (2)$$

According to (1), when $z=0$, we get from (2):

$$\sin\theta_1 = \sin\theta_2$$

$$\Rightarrow \theta_1 = \theta_2$$

6.5



According to General Geometric relation, we know $\angle APB = \frac{\theta}{2}$.

$$\text{And } \alpha = \frac{\theta - \theta}{2}$$

$$\Rightarrow AP = AB \cdot \sin(\frac{\theta}{2} - \alpha) = AB \cos \frac{\theta}{2} = AB \sin \frac{\theta}{2} = 2R \sin \frac{\theta}{2}$$

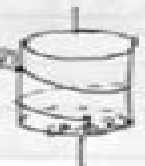
$$BP = AB \cdot \sin \alpha = 2R \cdot \cos \frac{\theta}{2}$$

$$\Rightarrow APB = 2R \cdot (\sin \frac{\theta}{2} + \cos \frac{\theta}{2}) = 2\sqrt{2} \sin(\frac{\theta}{2} + \frac{\pi}{4}) R$$

$$\Rightarrow (APB)_{\max} = 2\sqrt{2} R \text{ when } \theta = \frac{\pi}{2}, \text{ which is the real path.}$$

6.7

(2.4.2)



In cylinder coordinates, when R is const, the infinitesimal change in position corresponds to

$$ds = \sqrt{R^2 d\phi^2 + dz^2} = dz \sqrt{1 + R^2 \frac{d\phi^2}{dz^2}} = f(\phi, z) dz$$

$$\Rightarrow L = \int_R ds = \int_{\phi_1}^{\phi_2} f(\phi, z) dz$$

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Essential Classical Mechanics Choonkyu Lee, Hyunsoo Min, 2018-04-17 The authors deliver a highly readable text which should assure a continued supply of practitioners of classical mechanics and its applications Contemporary Physics This is a book on intermediate classical mechanics In this book classical mechanics is presented as a useful tool to analyze the physical universe and also as the base on which the whole

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Solution Manual For Classical Mechanics And Electrodynamics (Second Edition). Jon Magne Leinaas, 2025

Introduction To Classical Mechanics: Solutions To Problems John Dirk Walecka, 2020-08-24 The textbook Introduction to Classical Mechanics aims to provide a clear and concise set of lectures that take one from the introduction and application of Newton's laws up to Hamilton's principle of stationary action and the Lagrangian mechanics of continuous systems An extensive set of accessible problems enhances and extends the coverage It serves as a prequel to the author's recently published book entitled Introduction to Electricity and Magnetism based on an introductory course taught some time ago at Stanford with over 400 students enrolled Both lectures assume a good concurrent course in calculus and familiarity with basic concepts in physics the development is otherwise self contained As an aid for teaching and learning and as was previously done with the publication of Introduction to Electricity and Magnetism Solutions to Problems this additional book provides the solutions to the problems in the text Introduction to Classical Mechanics

The Mechanics Problem Solver Research and Education Association, 1995

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