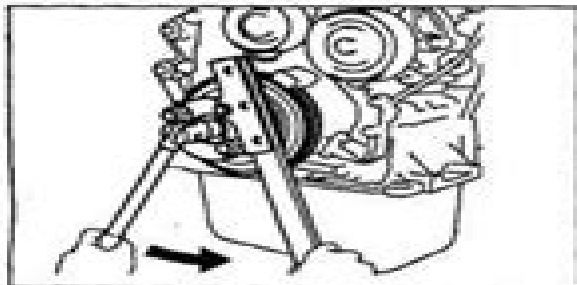


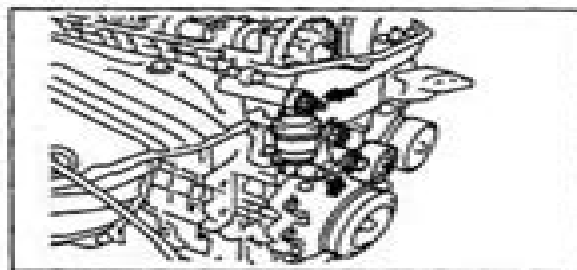
20. Снимите шкив коленчатого вала.
а) Выверните болт шкива при помощи спецприспособления.



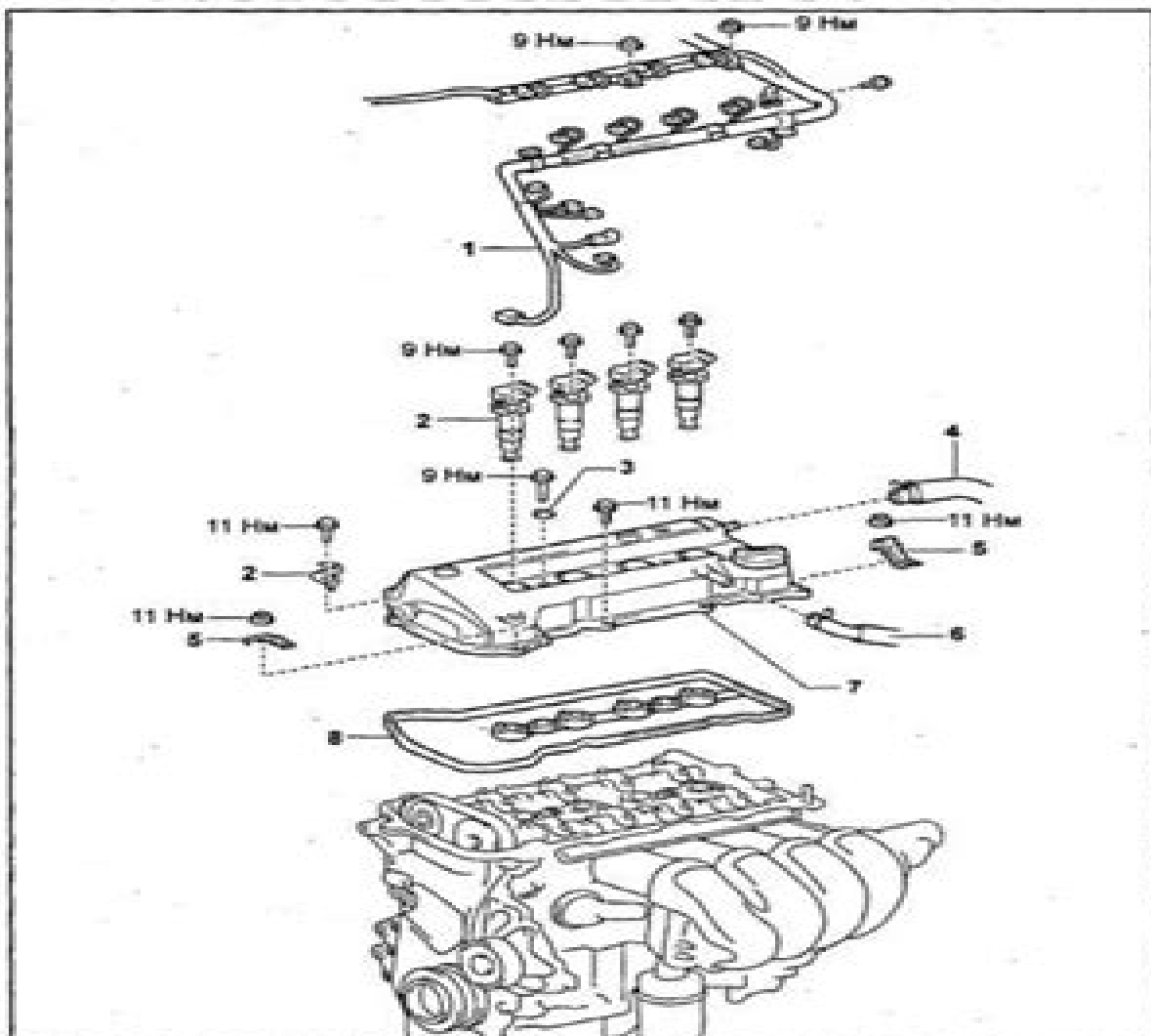
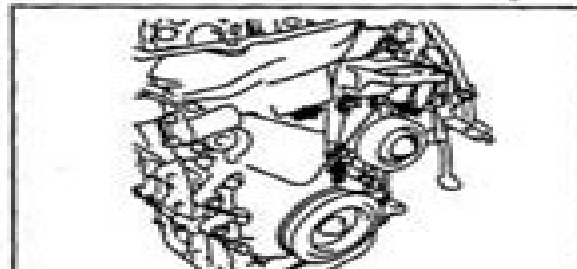
б) Снимите шкив коленчатого вала с помощью съемника.



21. Снимите натяжитель ремня привода навесных агрегатов, отвернув болт и гайку.



22. Снимите кронштейн правой опоры двигателя, отвернув три болта.



Снятие цепи привода ГРМ (этап 2). 1 - жгут проводов двигателя, 2 - катушка зажигания в сборе, 3 - шайба, 4, 6 - шланг системы принудительной вентиляции картера, 5 - кронштейн, 7 - крышка головки блока цилиндров, 8 - прокладка.

24. Снимите насос охлаждающей жидкости (см. главу "Система охлаждения").

25. Снимите датчик положения коленчатого вала (см. главу "Система зажигания").

26. Снимите крышку цепи привода ГРМ.

а) Отверните 11 болтов и гайку.

б) Используя шестигранный, выверните шпильку.

27. Снимите ротор датчика положения коленчатого вала.

28. Снимите натяжитель цепи привода ГРМ, отвернув болт.

29. Снимите цепь привода ГРМ и звездочку коленчатого вала.

При необходимости вставьте две отвертки между цепью и масляным насосом.

Control System Diagram 1zz Engine

Michal Rosen-Zvi



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Proceedings of the International Conference on Soft Computing Systems L. Padma Suresh, Bijaya Ketan Panigrahi, 2015-12-28 The book is a collection of high quality peer reviewed research papers presented in International Conference on Soft Computing Systems ICSCS 2015 held at Noorul Islam Centre for Higher Education Chennai India These research papers provide the latest developments in the emerging areas of Soft Computing in Engineering and Technology The book is organized in two volumes and discusses a wide variety of industrial engineering and scientific applications of the emerging techniques It presents invited papers from the inventors originators of new applications and advanced technologies

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characteristics of transient behavior the application of the root locus method to the design of control systems the use of the analog computer to simulate control systems state space methods digital control systems frequency response methods and system compensation

Control Systems Engineering Norman S. Nise,1992 Design of Control Systems A. Frank D'Souza,1988

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Introduction to Control System Analysis and Design Francis J. Hale,1973 Concentrates on classical control theory Contains chapters on controllers modern control theory advanced control systems

Control Systems Jesus C. De Sosa,2010-04-13 The intent of this book is to emphasize the basics of control system These basics include transfer function block diagram signal flow graph and the matrix approach in solving simultaneous differential equations Additionally they also include Bode plot realization diagram and stability analysis The book also shows digital control system as an extension of analog control system To illustrate these basics the author used extensive figures and tables Each figure consists of sketches and mathematical equations shown on its text Such an approach minimizes backward referencing from a figure to its text and vice versa After a careful study of the book an engineer should be able to design analyze or test a control system

Introduction to Control Systems Davinder K. Anand,R. B. Zmood,1995 Since the second edition of this classic text for students and engineers appeared in 1984 the use of computer aided design software has become an important adjunct to the study of control system analysis and design With this in mind the entire text has been recast enlarged and updated In addition the scope of the book has been extended so that it is suitable for students of mechanical and electrical engineering as well as other students of control systems Many of the classical analytical and graphical techniques have been retained because of their important conceptual role in understanding control system design although the use of computer techniques in their application is encouraged and emphasized The concept of a system S has been highlighted in the text and various mathematical representations of it by the transfer function and State equation are carefully examined in early chapters In discussing feedback control the concept of robustness is introduced as a means of studying the effect of parameter variation upon system performance Two new chapters on control strategies and plant sizing and on adaptive control have been added The chapters on control system design discrete time control and non linear control systems have been considerably expanded to cover such matters as pole placement design using state space methods digital compensators and Popov stability methods of analysis Dr D K Anand is both a Professor and Chairman of the Department of Mechanical Engineering at the University of Maryland USA Dr Anand has consulted widely in systems analysis for the US Government and for industry and is a prominent author on control and engineering subjects Dr R B Zmood is the Control Discipline Leader in the Department of Electrical Engineering at Royal Melbourne Institute of Technology Australia He has consulted widely both in Australia and in the USA on the industrial and military applications of control systems

Principles Of Control Systems U.A.Bakshi S.C.Goyal,2008 Open loop and closed loop systems

Servomechanism Basic structure of a feedback control system Dynamic Models and Responses Dynamic model of an RLC network State variable model Impulse response model Transfer function model Standard test disturbance signals and their models Transfer function model and dynamic response of a second order electrical system Control System Components Basic units of feedback control system Reduction of system block diagrams Signal flow graph Mason's gain rule Block diagram reduction using Mason's gain rule Operational amplifier used as an error detector Servo potentiometer DC and AC servomotors Tachogenerator Stepper motor Synchros Block diagram model of a typical control system using simplified subsystem Transfer function blocks Feedback Control System Characteristics Stability Sensitivity Disturbance rejection Steady state accuracy Transient and steady state responses of a second order system Effect of additional zeros and poles Desired closed loop pole locations and dominant poles Steady state error constants System type numbers and error compensation System Stability Analysis and Compensator Design System stability bounds Routh stability criterion Relative stability and range of stability Root locus concept System characteristic equation Plotting root loci Design of cascade lag lead compensation Minor loop rate feedback compensation Nyquist Criterion and Stability Margins Nyquist stability criterions Nyquist plot Gain and phase margins Bode plot of magnitude and phase and determination of stability margins Feedback System Performance Performance specifications in frequency domain Correlation between frequency domain and time domain specifications Constant M circles Nichols chart Stability margins from sensitivity function Design of cascade lag lead compensation using Bode plot Minor loop rate feedback compensation

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