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constant c $\lim_{x \rightarrow a} c = c$ $\lim_{x \rightarrow a} x = a$ $\lim_{x \rightarrow a} x^2 = a^2$ $\lim_{x \rightarrow a} \frac{1}{x} = \frac{1}{a}$ $\lim_{x \rightarrow a} \frac{1}{x^2} = \frac{1}{a^2}$

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web for example to apply the limit laws to a limit of the form $\lim_{x \rightarrow a} h(x)$ we require the function $h(x)$ to be defined over an open interval of the form (b, a) for a limit of the form $\lim_{x \rightarrow a} \frac{h(x)}{k(x)}$ we require the function $h(x)$ to be defined over an open interval of

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web sep 2 2020 this work involves designing and fabricating a simple pick and place arm type robot that could be used in handling of parts during different production process the production process may include

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web fig 1 block diagram of line follower robot fig 2 implemented line follower prototype model 2 pick and place robot the robotic arm is a type of mechanical arm which is usually programmable with similar functions to a human arm and human controlled based system the pick and place robotic arm consists of a robotic arm placed on a moving

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web here programmable logic and controller is used for controlling and operating robotic arm all the various problems of this process have been analyzed properly and have been taken into consideration while programming and designing the pick and

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web based on the user commands the robot moves and pick and place the objects the robotic arm used here is similar to a human arm which is programmed to perform the pick and place functions the remainder of this paper is organized as follows the section 2 provides information about the existing works section 3 gives details of the proposed

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