

ESTIMATION OF CURVATURES IN POINT SETS BASED ON GEOMETRIC ALGEBRA

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Abstract: For applications like segmentation, feature extraction and classification of point sets it is essential to know the principal curvatures and the corresponding principal directions. For the purpose of curvature estimation conformal geometric algebra promises to be a natural mathematical language: Local curvatures can be described with the help of osculating circles or spheres. On one hand, conformal geometric algebra is able to directly compute with these geometric objects, as well as with lines and planes needed for the description of vanishing curvature. On the other hand, distance measures for fitting these objects into point sets can be handled in a linear way, leading to efficient algorithms. In this paper we use conformal geometric algebra advantageously in order to locally compute continuous curvatures as well as principal curvatures of point sets without the need of costly pre-processing of raw data. We show results on artificial and real data. Numerical verification on artificial data shows the accuracy of our approach.

1 INTRODUCTION

The curvature of a surface is a feature which describes local surface properties in a well defined manner. Each certain location has a minimal and a maximal principal curvature with orthogonal principal directions. In (Alliez et al., 2003) this information is used to obtain lines of curvature and umbilical points as basis for a remeshing of surfaces. Other domains are feature extraction for local comparison of shapes (Gatzke et al., 2005), classification, registration or for instance the estimation of surface properties such as surface roughness (Lavoue, 2007) which uses this measure for object segmentation. Therefore, curvature estimation has become an important topic of research (Kalogerakis et al., 2007; Yang et al., 2006). Point set surfaces are very popular in computer graphics because they are powerful surface representations based on raw scanner data (Gross and Pfister, 2007), although it requires some effort to reconstruct the surface from these (noisy) point clouds (Hornung and Kobbe, 2006; Mederos et al., 2005; Kohler et al., 2004; Mitra et al., 2004; Adamson and Alexa, 2003). As a consequence, computing curvatures from

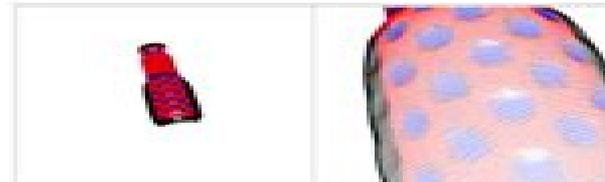


Figure 1: Point rendering of shape index estimated from a point, the shown point-set is the raw output of a structured light reconstruction system without preprocessing like smoothing or reduction. A pattern of concave areas and some noise caused by the reconstruction process can be observed at the surface of the bottle. The proposed algorithm extracts the curvature on a local neighborhood yielding a basis for object segmentation or feature detection.

point clouds without explicitly computing the surface (-mesh) is extremely difficult. Approaches to tackle this problem use statistics (Kalogerakis et al., 2007), or fitting of quadratic functions as local polynomial (Gois et al., 2006). In order to determine local cur-

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Table of Contents Estimation Of Curvatures In Point Sets Based On Geometric

1. Understanding the eBook Estimation Of Curvatures In Point Sets Based On Geometric
 - The Rise of Digital Reading Estimation Of Curvatures In Point Sets Based On Geometric
 - Advantages of eBooks Over Traditional Books
2. Identifying Estimation Of Curvatures In Point Sets Based On Geometric
 - Exploring Different Genres
 - Considering Fiction vs. Non-Fiction
 - Determining Your Reading Goals
3. Choosing the Right eBook Platform
 - Popular eBook Platforms
 - Features to Look for in an Estimation Of Curvatures In Point Sets Based On Geometric
 - User-Friendly Interface
4. Exploring eBook Recommendations from Estimation Of Curvatures In Point Sets Based On Geometric
 - Personalized Recommendations
 - Estimation Of Curvatures In Point Sets Based On Geometric User Reviews and Ratings
 - Estimation Of Curvatures In Point Sets Based On Geometric and Bestseller Lists
5. Accessing Estimation Of Curvatures In Point Sets Based On Geometric Free and Paid eBooks
 - Estimation Of Curvatures In Point Sets Based On Geometric Public Domain eBooks
 - Estimation Of Curvatures In Point Sets Based On Geometric eBook Subscription Services
 - Estimation Of Curvatures In Point Sets Based On Geometric Budget-Friendly Options
6. Navigating Estimation Of Curvatures In Point Sets Based On Geometric eBook Formats
 - ePub, PDF, MOBI, and More
 - Estimation Of Curvatures In Point Sets Based On Geometric Compatibility with Devices
 - Estimation Of Curvatures In Point Sets Based On Geometric Enhanced eBook Features
7. Enhancing Your Reading Experience
 - Adjustable Fonts and Text Sizes of Estimation Of Curvatures In Point Sets Based On Geometric
 - Highlighting and Note-Taking Estimation Of Curvatures In Point Sets Based On Geometric
 - Interactive Elements Estimation Of Curvatures In Point Sets Based On Geometric

8. Staying Engaged with Estimation Of Curvatures In Point Sets Based On Geometric
 - Joining Online Reading Communities
 - Participating in Virtual Book Clubs
 - Following Authors and Publishers Estimation Of Curvatures In Point Sets Based On Geometric
9. Balancing eBooks and Physical Books Estimation Of Curvatures In Point Sets Based On Geometric
 - Benefits of a Digital Library
 - Creating a Diverse Reading Collection Estimation Of Curvatures In Point Sets Based On Geometric
10. Overcoming Reading Challenges
 - Dealing with Digital Eye Strain
 - Minimizing Distractions
 - Managing Screen Time
11. Cultivating a Reading Routine Estimation Of Curvatures In Point Sets Based On Geometric
 - Setting Reading Goals Estimation Of Curvatures In Point Sets Based On Geometric
 - Carving Out Dedicated Reading Time
12. Sourcing Reliable Information of Estimation Of Curvatures In Point Sets Based On Geometric
 - Fact-Checking eBook Content of Estimation Of Curvatures In Point Sets Based On Geometric
 - Distinguishing Credible Sources
13. Promoting Lifelong Learning
 - Utilizing eBooks for Skill Development
 - Exploring Educational eBooks
14. Embracing eBook Trends
 - Integration of Multimedia Elements
 - Interactive and Gamified eBooks

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