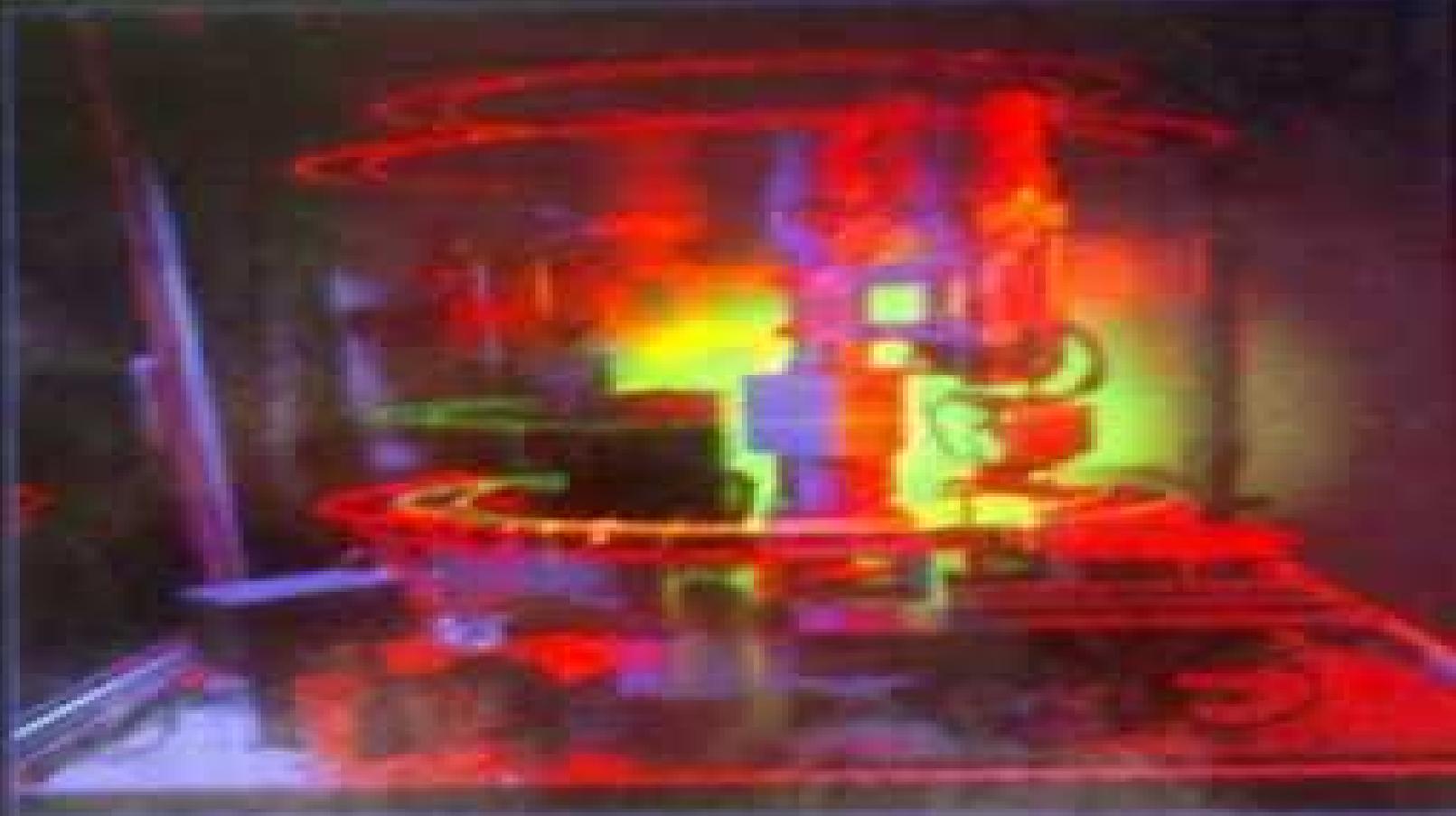


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THIRD EDITION*



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Control Allocation for Spacecraft Under Actuator Faults Qinglei Hu, Bo Li, Bing Xiao, Youmin Zhang, 2021-03-13 This book provides a systematical and comprehensive description of some facets of modeling designing analyzing and exploring the control allocation and fault tolerant control problems for over actuated spacecraft attitude control system under actuator failures system uncertainties and disturbances The book intends to provide a unified platform for understanding and applicability of the fault tolerant attitude control and control allocation for different purposes in aerospace engineering and some related fields And it is particularly suited for readers who are interested to learn solutions in spacecraft attitude control system design and related engineering applications

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assist engineers Offers a clear systematic reference on fault tolerant control and attitude control for spacecraft *Feedback Control of Dynamic Systems, Global Edition* Gene F. Franklin, David Powell, Abbas F. Emami-Naeini, 2019-05-08 For courses in electrical computing engineering Feedback control fundamentals with context case studies and a focus on design Feedback Control of Dynamic Systems 8th Edition covers the material that every engineer needs to know about feedback control including concepts like stability tracking and robustness Each chapter presents the fundamentals along with comprehensive worked out examples all within a real world context and with historical background provided The text is devoted to supporting students equally in their need to grasp both traditional and more modern topics of digital control and the author's focus on design as a theme early on rather than focusing on analysis first and incorporating design much later An entire chapter is devoted to comprehensive case studies and the 8th Edition has been revised with up to date information along with brand new sections problems and examples The full text downloaded to your computer With eBooks you can search for key concepts words and phrases make highlights and notes as you study share your notes with friends eBooks are downloaded to your computer and accessible either offline through the Bookshelf available as a free download available online and also via the iPad and Android apps Upon purchase you'll gain instant access to this eBook Time limit The eBooks products do not have an expiry date You will continue to access your digital ebook products whilst you have your Bookshelf installed

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Feedback Control of Dynamics Systems Gene Franklin, Abbas Emami-Naeini, David Powell, 1994 *Feedback and Control for Everyone* Pedro Albertos, Iven Mareels, 2010-06-10 This intriguing and motivating book presents the basic ideas and understanding of control signals and systems for readers interested in engineering and science Through a series of examples the book explores both the theory and the practice of control

Feedback Control Theory in Stochastic Dynamical Systems Ashkan Balouchi, 2016 **Dynamical Systems and Microphysics** Austin Blaquiere, 2012-12-02 Dynamical Systems and Microphysics Control Theory and Mechanics contains the proceedings of the Third International Seminar on Mathematical Theory of Dynamical Systems and Microphysics held in Udine Italy on September 4-9 1983 The papers explore the mechanics and optimal control of dynamical systems and cover topics ranging from complete controllability and stability to feedback control in general relativity adaptive control for uncertain dynamical systems geometry of canonical transformations and homogeneity in mechanics This book is comprised of 14 chapters and begins by discussing the relationship between complete controllability and Poisson stabilizability in relation to Liapounov stabilizability The next chapter looks at the conditions that must be met in order to control a dynamical system in an optimal fashion The theory of optimal feedback control is used as an approach to the dynamics of a mass point in general relativity The theory of reachability with feedback control is also used as an approach to geometrical optics in the frame of general relativity The final chapter describes a system theoretic framework for the study of Hamiltonian systems with external forces This monograph is intended primarily for researchers and graduate students in theoretical physics mechanics control and system theory and mathematics It may also be read profitably by philosophers of science and to some extent by those who have a keen interest in basic questions of contemporary mechanics and physics and who possess some background in the physical and mathematical sciences

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