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•12-8. A particle is moving along a straight line with the acceleration $a = (12t - 2t^{3/2}) \text{ ft/s}^2$, where t is in seconds. Determine the velocity and the position of the particle as a function of time. When $t = 0$, $v = 0$ and $s = 15 \text{ ft}$.

Velocity:

$$(+\curvearrowright) \quad dv = a \, dt$$

$$\int_0^v dv = \int_0^t (12t - 2t^{3/2}) \, dt$$

$$v|_0^v = (6t^2 - 2t^{5/2})|_0^t$$

$$v = (6t^2 - 2t^{5/2}) \text{ ft/s} \quad \text{Ans.}$$

Position: Using this result and the initial condition $s = 15 \text{ ft}$ at $t = 0 \text{ s}$,

$$(+\curvearrowright) \quad ds = v \, dt$$

$$\int_{15}^s ds = \int_0^t (6t^2 - 2t^{5/2}) \, dt$$

$$s|_{15}^s = \left(2t^3 - \frac{4}{7}t^{7/2} \right)|_0^t$$

$$s = \left(2t^3 - \frac{4}{7}t^{7/2} + 15 \right) \text{ ft} \quad \text{Ans.}$$

12-6. A ball is released from the bottom of an elevator which is traveling upward with a velocity of 6 ft/s . If the ball strikes the bottom of the elevator shaft in 3 s , determine the height of the elevator from the bottom of the shaft at the instant the ball is released. Also, find the velocity of the ball when it strikes the bottom of the shaft.

Kinematics When the ball is released, its velocity will be the same as the elevator at the instant of release. Thus, $v_0 = 6 \text{ ft/s}$. Also, $t = 3 \text{ s}$, $s_0 = 0$, $s = -h$, and $a_y = -32.2 \text{ ft/s}^2$.

$$(+\uparrow) \quad s = s_0 + v_0 t + \frac{1}{2} a_y t^2$$

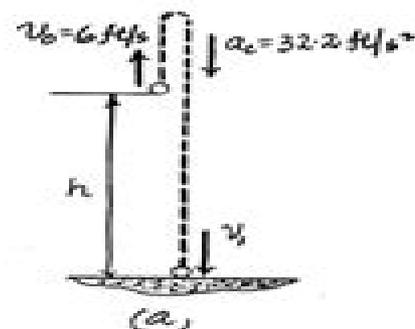
$$-h = 0 + 6(3) + \frac{1}{2}(-32.2)(3^2)$$

$$h = 127 \text{ ft} \quad \text{Ans.}$$

$$(+\uparrow) \quad v = v_0 + a_y t$$

$$v = 6 + (-32.2)(3)$$

$$= -90.6 \text{ ft/s} = 90.6 \text{ ft/s} \downarrow \quad \text{Ans.}$$



Engineering Mechanics Dynamics 12th Solutions

James L. Meriam



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Engineering Dynamics Course Companion Part 1 Particles Kinematics and Kinetics is a supplemental textbook intended to assist students especially visual learners in their approach to Sophomore level Engineering Dynamics This text covers particle kinematics and kinetics and emphasizes Newtonian Mechanics Problem Solving Skills in an accessible and fun format organized to coincide with the first half of a semester schedule many instructors choose and supplied with numerous example problems While this book addresses Particle Dynamics a separate book Part 2 is available that covers Rigid Body Dynamics

Engineering Mechanics: Dynamics Stephen Timoshenko, Donovan Harold Young, 1956 Engineering mechanics: dynamics (12th ed.). R. C. Hibbeler, 2010 Complex Variable Function Solutions in the Mechanical Analysis of Tunnels Aizhong Lu, Huaning Wang, Luqing Zhang, 2025-03-03

This book covers the mechanical problems of tunnels in traffic hydraulic and mining engineering By extending the complex variable method in mechanical analysis it proposes accurate analytical solutions for tunnels The solutions are further applied to the back analysis of tunnels hole shape optimization support design and estimation of tunnel stability The considered rock characteristics involve elasticity elastoplasticity viscoelasticity and anisotropy and various geometric conditions are included such as circular noncircular single multiple tunnels with without support at deep shallow depths Some original achievements are provided including new mapping functions for complex regions precise determination of the noncircular plastic zone around single twin tunnels and related elastoplastic solutions and quantitative analysis of the interaction between rock and the support which are new developments of theory and method in rock mechanics The proposed analytical solutions are reliable tools to initially estimate the design parameters and achieve optimal design providing guidance in the conceptual stage of the design process They can clearly reveal the influences of parameters in functional form and provide a benchmark against which the overall correctness of numerical analyses can be assessed This book summarizes the author s research achievements over more than 20 years It is a valuable reference for professionals working in geotechnical engineering

Theory of Gyroscopic Effects for Rotating Objects Ryspek Usubamatov, 2022-06-30

This book highlights an analytical solution for the dynamics of axially rotating objects It also presents the theory of gyroscopic effects explaining their physics and using mathematical models of Euler s form for the motion of movable spinning objects to demonstrate these effects The major themes and approaches are represented by the spinning disc and the action of the system of interrelated inertial torques generated by the centrifugal and Coriolis forces as well as the change in the angular momentum The interrelation of inertial torques is based on the dependency of the angular velocities of the motions of the spinning objects around axes by the

principle of mechanical energy conservation These kinetically interrelated torques constitute the fundamental principles of the mechanical gyroscope theory that can be used for any rotating objects of different designs like rings cones spheres paraboloids propellers etc Lastly the mathematical models for the gyroscopic effects are validated by practical tests The 2nd edition became necessary due to new development and corrections of mathematical expressions It contains new chapters about the Tippe top inversion and inversion of the spinning object in an orbital flight and the boomerang aerodynamics

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web kinetics branch of classical mechanics that concerns the effect of forces and torques on the motion of bodies having mass authors using the term kinetics apply the nearly synonymous name dynamics $q v$ to the classical mechanics of moving bodies this is in contrast to statics which concerns bodies at rest under equilibrium conditions

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