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core problems in robotics such as motion planning sensor based planning manipulation and assembly planning They also examine the application o Three Dimensional Frictional Rigid Body Impacts Vivek Bhatt,1995 *Computer Animation '96* ,1996 *Radar Target Discrimination Using Neural Networks* Chang-Ying Tsai,1995 *Robotica* ,1993 **Bulletin of Pure & Applied Sciences** ,2003 *Proceedings of the IEEE International Conference on Industrial Technology* ,1994 *Bibliographic Guide to Technology* New York Public Library. Research Libraries,1989

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