



Discrete Sliding Mode Control For Robust Tracking Of Time

TENCON (2002, Beijing)



Discrete Sliding Mode Control For Robust Tracking Of Time:

Sliding Mode Control Using Novel Sliding Surfaces B. Bandyopadhyay, Fulwani Deepak, Kyung-Soo Kim, 2009-09-23

After a survey paper by Utkin in the late 1970s sliding mode control methodologies emerged as an effective tool to tackle uncertainty and disturbances which are inevitable in most of the practical systems. Sliding mode control is a particular class of variable structure control which was introduced by Emel'yanov and his colleagues. The design paradigms of sliding mode control has now become a mature design technique for the design of robust controller of uncertain system. In sliding mode technique the state trajectory of the system is constrained on a chosen manifold or within some neighborhood thereof by an appropriate control action. This manifold is also called a switching surface or a sliding surface. During sliding mode system dynamics is governed by the chosen manifold which results in a well celebrated invariance property towards certain classes of disturbance and model mismatches. The purpose of this monograph is to give a different dimension to sliding surface design to achieve high performance of the system. Design of the switching surface is vital because the closed loop dynamics is governed by the parameters of the sliding surface. Therefore sliding surface should be designed to meet the closed loop specifications. Many systems demand high performance with robustness. To address this issue of achieving high performance with robustness we propose nonlinear surfaces for different classes of systems. The nonlinear surface is designed such that it changes the system's closed loop damping ratio from its initial low value to a final high value.

[Proceedings of the 2009 International Conference on Signals, Systems and Automation \(ICSSA 2009\)](#) Himanshu Soni, 2010-04-30. This book is a collection of papers from the 2009 International Conference on Signals Systems and Automation ICSSA 2009. The conference at a glance. Pre-conference Workshops Tutorials on 27th Dec 2009. Five Plenary talks. Paper Poster Presentation 28-29 Dec 2009. Demonstrations by SKYVIEW Inc, SLS Inc, BSNL, Baroda Electric Meters, SIS. On-line paper submission facility on website. 200 papers are received from India and abroad. Delegates from different countries including Poland, Iran, USA. Delegates from 16 states of India. Conference website is seen by more than 3000 persons across the world, 27 countries and 120 cities.

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