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COMPUTER & MACHINE VISION

Theory
Algorithms
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Machine Vision E. R. Davies,2012-04-18 Computer and Machine Vision Theory Algorithms Practicalities previously entitled Machine Vision clearly and systematically presents the basic methodology of computer and machine vision covering the essential elements of the theory while emphasizing algorithmic and practical design constraints This fully revised fourth edition has brought in more of the concepts and applications of computer vision making it a very comprehensive and up to date tutorial text suitable for graduate students researchers and R D engineers working in this vibrant subject Key features include Practical examples and case studies give the ins and outs of developing real world vision systems giving engineers the realities of implementing the principles in practice New chapters containing case studies on surveillance and driver assistance systems give practical methods on these cutting edge applications in computer vision Necessary mathematics and essential theory are made approachable by careful explanations and well illustrated examples Updated content and new sections cover topics such as human iris location image stitching line detection using RANSAC performance measures and hyperspectral imaging The recent developments section now included in each chapter will be useful in bringing students and practitioners up to date with the subject Mathematics and essential theory are made approachable by careful explanations and well illustrated examples Updated content and new sections cover topics such as human iris location image stitching line detection using RANSAC performance measures and hyperspectral imaging The recent developments section now included in each chapter will be useful in bringing students and practitioners up to date with the subject **Cumulative Book Index**

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Parallel Computing Wouter Joosen,Elie Milgrom,1992 *Encyclopedia of Library and Information Science* Allen Kent,Harold Lancour,William Z. Nasri,Jay Elwood Daily,1968 Vol 73 index to v 48 72 **Advanced Robotics: 1989** Kenneth J. Waldron,1990-01-11 The Fourth International Conference on Advanced Robotics was held in Columbus Ohio U S A on June 13th to 15th 1989 The first two conferences in this series were held in Tokyo The third was held in Versailles France in October 1987 The International Conference on Advanced Robotics is affiliated with the International Federation of Robotics This conference was sponsored by The Ohio State University The American Society of Mechanical Engineers was a cooperating co sponsor The objective of the International Conference on Advanced Robotics is to provide an international exchange of information on the topic of advanced robotics This was adopted as one of the themes for international research cooperation at a meeting of representatives of seven industrialized countries held in Williamsburg U S A in May 1983 The present conference is truly international in character with contributions from authors of twelve countries Bulgaria Canada France Great Britain India Italy Japan Peoples Republic of China Poland Republic of China Spain United States of America The subject matter of the papers is equally diverse covering most technical areas of robotics The authors are distinguished They are leaders in the field in their respective countries The International Conference on Advanced Robotics has always particularly encouraged papers oriented to the design of robotic systems or to research directed at advanced applications in service robotics construction nuclear power agriculture mining underwater systems and space systems

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