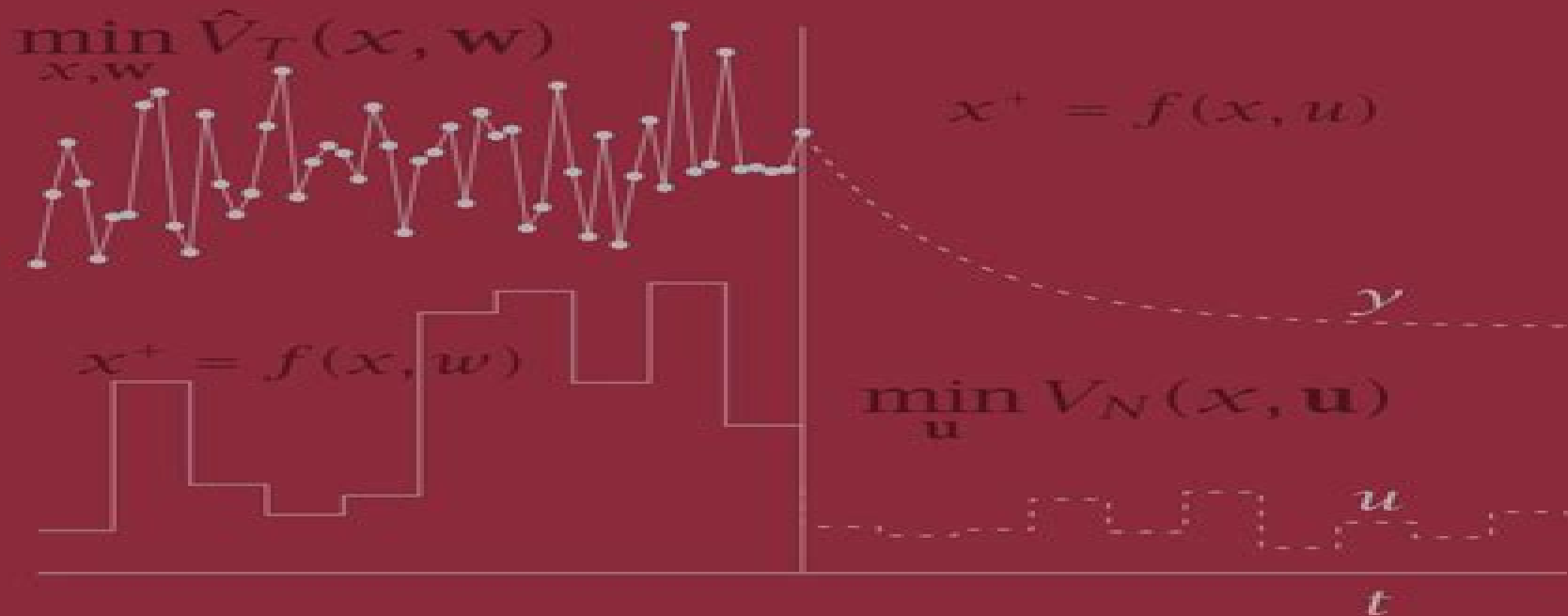


Model Predictive Control: Theory, Computation, and Design

2nd Edition

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ideas and useful tools techniques for their works Recent Advances in Model Predictive Control Timm Faulwasser,Matthias A. Müller,Karl Worthmann,2021-04-17 This book focuses on distributed and economic Model Predictive Control MPC with applications in different fields MPC is one of the most successful advanced control methodologies due to the simplicity of the basic idea measure the current state predict and optimize the future behavior of the plant to determine an input signal and repeat this procedure ad infinitum and its capability to deal with constrained nonlinear multi input multi output systems While the basic idea is simple the rigorous analysis of the MPC closed loop can be quite involved Here distributed means that either the computation is distributed to meet real time requirements for very large scale systems or that distributed agents act autonomously while being coupled via the constraints and or the control objective In the latter case communication is necessary to maintain feasibility or to recover system wide optimal performance The term economic refers to general control tasks and thus goes beyond the typically predominant control objective of set point stabilization Here recently developed concepts like strict dissipativity of optimal control problems or turnpike properties play a crucial role The book collects research and survey articles on recent ideas and it provides perspectives on current trends in nonlinear model predictive control Indeed the book is the outcome of a series of six workshops funded by the German Research Foundation DFG involving early stage career scientists from different countries and from leading European industry stakeholders **Systems Theory in Data and Optimization** Julian Berberich,Andrea Iannelli,Frank Allgöwer,2025-09-26 This book contains the proceedings of the Symposium on Systems Theory in Data and Optimization SysDO held in Stuttgart Germany from 30th September to 2nd October 2024 It addresses theoretical and practical research questions arising at the intersection of systems and control theory data and optimization The increasing prevalence of cyber physical systems sparks the need for new methods to integrate measured data and different forms of feedback especially optimization based feedback inside the decision making mechanism There are distinctive challenges that arise in this scenario such as the existence of different time scales the need to guarantee sufficient richness of the collected data and the effect of suboptimal decisions under uncertainty This book presents new methods and applications addressing these challenges This book is a valuable source on latest research findings spanning diverse topics including data driven and learning based control theory and applications of machine learning model predictive control and optimization *Emerging Electronics and Automation* Peter Han Joo Chong,Akhtar Kalam,Antonio Pascoal,Manas Kumar Bera,2022-11-09 This book constitutes peer reviewed proceedings of the International Conference on Emerging Electronics and Automation E2A 2021 The book presents new ideas research findings and novel techniques in the fields of sensors and instrumentation automation and control artificial intelligence MEMS sensors soft computing signal processing and communication It includes contributions received from both academia and industry The proceedings will be helpful for beginners as well as advanced researchers in the area of automation and other allied fields Advanced Model Predictive Control for Autonomous Marine

Vehicles Yang Shi,Chao Shen,Henglai Wei,Kunwu Zhang,2023-02-13 This book provides a comprehensive overview of marine control system design related to underwater robotics applications In particular it presents novel optimization based model predictive control strategies to solve control problems appearing in autonomous underwater vehicle applications These novel approaches bring unique features such as constraint handling prioritization between multiple design objectives optimal control performance and robustness against disturbances and uncertainties into the control system design They therefore form a more general framework to design marine control systems and can be widely applied Advanced Model Predictive Control for Autonomous Marine Vehicles balances theoretical rigor providing thorough analysis and developing provably correct design conditions and application perspectives addressing practical system constraints and implementation issues Starting with a fixed point positioning problem for a single vehicle and progressing to the trajectory tracking and path following problem of the vehicle and then to the coordination control of a large scale multi robot team this book addresses the motion control problems increasing their level of challenge step by step At each step related subproblems such as path planning thrust allocation collision avoidance and time constraints for real time implementation are also discussed with solutions In each chapter of this book compact and illustrative examples are provided to demonstrate the design and implementation procedures As a result this book is useful for both theoretical study and practical engineering design and the tools provided in the book are readily applicable for real world implementation

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