

VOLUME ONE

Second Edition

Dynamic Programming AND Optimal Control

DIMITRI P. BERTSEKAS

Dynamic Programming Optimal Control Vol I

**Alessandro Chiuso, Augusto
Ferrante, Stefano Pinzoni**



Dynamic Programming Optimal Control Vol I:

Dynamic Programming and Optimal Control Dimitri Bertsekas, 2012-10-23 This is the leading and most up to date textbook on the far ranging algorithmic methodology of Dynamic Programming which can be used for optimal control Markovian decision problems planning and sequential decision making under uncertainty and discrete combinatorial optimization The treatment focuses on basic unifying themes and conceptual foundations It illustrates the versatility power and generality of the method with many examples and applications from engineering operations research and other fields It also addresses extensively the practical application of the methodology possibly through the use of approximations and provides an extensive treatment of the far reaching methodology of Neuro Dynamic Programming Reinforcement Learning Among its special features the book 1 provides a unifying framework for sequential decision making 2 treats simultaneously deterministic and stochastic control problems popular in modern control theory and Markovian decision popular in operations research 3 develops the theory of deterministic optimal control problems including the Pontryagin Minimum Principle 4 introduces recent suboptimal control and simulation based approximation techniques neuro dynamic programming which allow the practical application of dynamic programming to complex problems that involve the dual curse of large dimension and lack of an accurate mathematical model 5 provides a comprehensive treatment of infinite horizon problems in the second volume and an introductory treatment in the first volume

Reinforcement Learning and Optimal Control Dimitri Bertsekas, 2019-07-01 This book considers large and challenging multistage decision problems which can be solved in principle by dynamic programming DP but their exact solution is computationally intractable We discuss solution methods that rely on approximations to produce suboptimal policies with adequate performance These methods are collectively known by several essentially equivalent names reinforcement learning approximate dynamic programming neuro dynamic programming They have been at the forefront of research for the last 25 years and they underlie among others the recent impressive successes of self learning in the context of games such as chess and Go Our subject has benefited greatly from the interplay of ideas from optimal control and from artificial intelligence as it relates to reinforcement learning and simulation based neural network methods One of the aims of the book is to explore the common boundary between these two fields and to form a bridge that is accessible by workers with background in either field Another aim is to organize coherently the broad mosaic of methods that have proved successful in practice while having a solid theoretical and or logical foundation This may help researchers and practitioners to find their way through the maze of competing ideas that constitute the current state of the art This book relates to several of our other books Neuro Dynamic Programming Athena Scientific 1996 Dynamic Programming and Optimal Control 4th edition Athena Scientific 2017 Abstract Dynamic Programming 2nd edition Athena Scientific 2018 and Nonlinear Programming Athena Scientific 2016 However the mathematical style of this book is somewhat different While we provide a rigorous albeit short mathematical account of the

theory of finite and infinite horizon dynamic programming and some fundamental approximation methods we rely more on intuitive explanations and less on proof based insights Moreover our mathematical requirements are quite modest calculus a minimal use of matrix vector algebra and elementary probability mathematically complicated arguments involving laws of large numbers and stochastic convergence are bypassed in favor of intuitive explanations The book illustrates the methodology with many examples and illustrations and uses a gradual expository approach which proceeds along four directions a From exact DP to approximate DP We first discuss exact DP algorithms explain why they may be difficult to implement and then use them as the basis for approximations b From finite horizon to infinite horizon problems We first discuss finite horizon exact and approximate DP methodologies which are intuitive and mathematically simple and then progress to infinite horizon problems c From deterministic to stochastic models We often discuss separately deterministic and stochastic problems since deterministic problems are simpler and offer special advantages for some of our methods d From model based to model free implementations We first discuss model based implementations and then we identify schemes that can be appropriately modified to work with a simulator The book is related and supplemented by the companion research monograph Rollout Policy Iteration and Distributed Reinforcement Learning Athena Scientific 2020 which focuses more closely on several topics related to rollout approximate policy iteration multiagent problems discrete and Bayesian optimization and distributed computation which are either discussed in less detail or not covered at all in the present book The author s website contains class notes and a series of videolectures and slides from a 2021 course at ASU which address a selection of topics from both books

Computational Intelligence - Volume I Hisao

Ishibuchi,2015-12-30 Computational intelligence is a component of Encyclopedia of Technology Information and Systems Management Resources in the global Encyclopedia of Life Support Systems EOLSS which is an integrated compendium of twenty one Encyclopedias Computational intelligence is a rapidly growing research field including a wide variety of problem solving techniques inspired by nature Traditionally computational intelligence consists of three major research areas Neural Networks Fuzzy Systems and Evolutionary Computation Neural networks are mathematical models inspired by brains Neural networks have massively parallel network structures with many neurons and weighted connections Whereas each neuron has a simple input output relation a neural network with many neurons can realize a highly non linear complicated mapping Connection weights between neurons can be adjusted in an automated manner by a learning algorithm to realize a non linear mapping required in a particular application task Fuzzy systems are mathematical models proposed to handle inherent fuzziness in natural language For example it is very difficult to mathematically define the meaning of cold in everyday conversations such as It is cold today and Can I have cold water The meaning of cold may be different in a different situation Even in the same situation a different person may have a different meaning Fuzzy systems offer a mathematical mechanism to handle inherent fuzziness in natural language As a result fuzzy systems have been successfully applied to real world

problems by extracting linguistic knowledge from human experts in the form of fuzzy IF THEN rules Evolutionary computation includes various population based search algorithms inspired by evolution in nature Those algorithms usually have the following three mechanisms fitness evaluation to measure the quality of each solution selection to choose good solutions from the current population and variation operators to generate offspring from parents Evolutionary computation has high applicability to a wide range of optimization problems with different characteristics since it does not need any explicit mathematical formulations of objective functions For example simulation based fitness evaluation is often used in evolutionary design Subjective fitness evaluation by a human user is also often used in evolutionary art and music These volumes are aimed at the following five major target audiences University and College students Educators Professional practitioners Research personnel and Policy analysts managers and decision makers

Dynamic programming and optimal control, vol. 2 Dimitri P. Bertsekas, 2000

Modeling, Estimation and Control Alessandro Chiuso, Augusto Ferrante, Stefano Pinzoni, 2007-10-24 This Festschrift is intended as a homage to our esteemed colleague friend and maestro Giorgio Picci on the occasion of his sixty fth birthday We have known Giorgiosince our undergraduate studies at the University of Padova where we first experienced his fascinating teaching in the class of System Identification While progressing through the PhD program then continuing to collaborate with him and eventually becoming colleagues we have had many opportunities to appreciate the value of Giorgio as a professor and a scientist and chiefy as a person We learned a lot from him and we feel indebted for his scientific guidance his constant support encouragement and enthusiasm For these reasons we are proud to dedicate this book to Giorgio The articles in the volume will be presented by prominent researchers at the Ternational Conference on Modeling Estimation and Control A Symposium in Honor of Giorgio Picci on the Occasion of his Sixty Fifth Birthday to be held in Venice on October 4 5 2007 The material covers a broad range of topics in mathematical systems theory estimation identification and control reflecting the wide network of scientific relationships established during the last thirty years between the authors and Giorgio Critical discussion of fundamental concepts close collaboration on specific topics joint research programs in this group of talented people have nourished the development of the field where Giorgio has contributed to establishing several cornerstones

Dynamic Optimization Karl Hinderer, Ulrich Rieder, Michael Stieglitz, 2017-01-12 This book explores discrete time dynamic optimization and provides a detailed introduction to both deterministic and stochastic models Covering problems with finite and infinite horizon as well as Markov renewal programs Bayesian control models and partially observable processes the book focuses on the precise modelling of applications in a variety of areas including operations research computer science mathematics statistics engineering economics and finance Dynamic Optimization is a carefully presented textbook which starts with discrete time deterministic dynamic optimization problems providing readers with the tools for sequential decision making before proceeding to the more complicated stochastic models The authors present complete and simple proofs and illustrate the main results with numerous examples

and exercises without solutions With relevant material covered in four appendices this book is completely self contained

CONTROL SYSTEMS, ROBOTICS AND AUTOMATION - Volume I Heinz Unbehauen,2009-10-11 This Encyclopedia of Control Systems Robotics and Automation is a component of the global Encyclopedia of Life Support Systems EOLSS which is an integrated compendium of twenty one Encyclopedias This 22 volume set contains 240 chapters each of size 5000 30000 words with perspectives applications and extensive illustrations It is the only publication of its kind carrying state of the art knowledge in the fields of Control Systems Robotics and Automation and is aimed by virtue of the several applications at the following five major target audiences University and College Students Educators Professional Practitioners Research Personnel and Policy Analysts Managers and Decision Makers and NGOs Control Applications of Nonlinear Programming and Optimization 1989 H.B. Siguerdidjane,P. Bernhard,2014-07-04 These Proceedings provide valuable information on the exchange of ideas between scientists who apply nonlinear programming and optimization to real world control problems and those who develop new methods algorithms and software The papers deal with windshear problems optimization of aircraft and spacecraft trajectories optimal control for robots the optimization of urban traffic control general mechanical systems multilevel inventory systems and robust control *Optimal Control of Dynamic Operations Research Models* Michael M. Connors,Daniel Teichroew,1967 The book is a survey of the application of variational methods to dynamic operations research models resulting from a study under Ford Foundation grants done at the Graduate School of Business Stanford University *Proceedings of the International Conference on Control and Information* 1995 Wing Shing Wong,1995-06-22

Abstract Dynamic Programming Dimitri Bertsekas,2022-01-01 This is the 3rd edition of a research monograph providing a synthesis of old research on the foundations of dynamic programming DP with the modern theory of approximate DP and new research on semicontractive models It aims at a unified and economical development of the core theory and algorithms of total cost sequential decision problems based on the strong connections of the subject with fixed point theory The analysis focuses on the abstract mapping that underlies DP and defines the mathematical character of the associated problem The discussion centers on two fundamental properties that this mapping may have monotonicity and weighted sup norm contraction It turns out that the nature of the analytical and algorithmic DP theory is determined primarily by the presence or absence of these two properties and the rest of the problem s structure is largely inconsequential New research is focused on two areas 1 The ramifications of these properties in the context of algorithms for approximate DP and 2 The new class of semicontractive models exemplified by stochastic shortest path problems where some but not all policies are contractive The 3rd edition is very similar to the 2nd edition except for the addition of a new chapter Chapter 5 which deals with abstract DP models for sequential minimax problems and zero sum games The book is an excellent supplement to several of our books Neuro Dynamic Programming Athena Scientific 1996 Dynamic Programming and Optimal Control Athena Scientific 2017 Reinforcement Learning and Optimal Control Athena Scientific 2019 and Rollout Policy Iteration and Distributed

Reinforcement Learning Athena Scientific 2020 **1995 IEEE Conference on Control Applications** IEEE Control Systems Society,1995 Encyclopedia of Optimization Christodoulos A. Floudas,Panos M. Pardalos,2008-09-04 The goal of the Encyclopedia of Optimization is to introduce the reader to a complete set of topics that show the spectrum of research the richness of ideas and the breadth of applications that has come from this field The second edition builds on the success of the former edition with more than 150 completely new entries designed to ensure that the reference addresses recent areas where optimization theories and techniques have advanced Particularly heavy attention resulted in health science and transportation with entries such as Algorithms for Genomics Optimization and Radiotherapy Treatment Design and Crew Scheduling **Artificial Intelligence in Industrial Decision Making, Control and Automation** S.G. Tzafestas,H. B. Verbruggen,2012-12-06 This book is concerned with Artificial Intelligence AI concepts and techniques as applied to industrial decision making control and automation problems The field of AI has been expanded enormously during the last years due to that solid theoretical and application results have accumulated During the first stage of AI development most workers in the field were content with illustrations showing ideas at work on simple problems Later as the field matured emphasis was turned to demonstrations that showed the capability of AI techniques to handle problems of practical value Now we arrived at the stage where researchers and practitioners are actually building AI systems that face real world and industrial problems This volume provides a set of twenty four well selected contributions that deal with the application of AI to such real life and industrial problems These contributions are grouped and presented in five parts as follows Part 1 General Issues Part 2 Intelligent Systems Part 3 Neural Networks in Modelling Control and Scheduling Part 4 System Diagnostics Part 5 Industrial Robotic Manufacturing and Organizational Systems Part 1 involves four chapters providing background material and dealing with general issues such as the conceptual integration of qualitative and quantitative models the treatment of timing problems at system integration and the investigation of correct reasoning in interactive man robot systems Journal of Dynamic Systems, Measurement, and Control ,1999 Journal of Guidance, Control, and Dynamics ,2008 Numerical Optimisation of Dynamic Systems Laurence Charles Ward Dixon,G. P. Szegő,1980 **Fiftieth Anniversary, 1912-1962** Institute of Radio Engineers,1962 U.S. Government Research & Development Reports ,1970 Control Theory: Elements of modern control theory Arthur L. Greensite,1970 Mainly for the aerospace engineer who is concerned with the design of automatic control systems for space vehicles

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Dynamic Programming Optimal Control Vol I Introduction

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