

# Control Systems with Scilab

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## A simple first order system

```
// Defining a first order system:  
s = %s // The quicker alternative to using s =  
    poly(0, 's')  
K = 1, T = 1 // Gain and time constant  
SimpleSys = syslin('c', K/(1+T*s))
```

# Control Systems With Scilab

**Annelies Wilder-Smith**



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