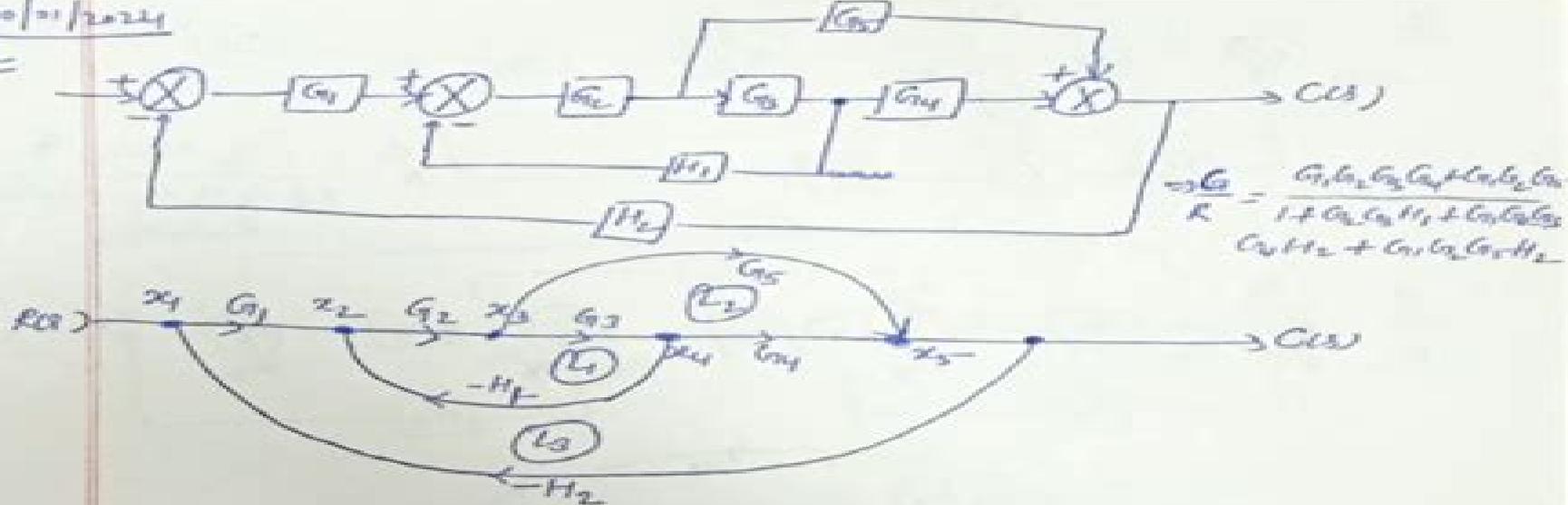


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$$\frac{C}{R} = \frac{G_1 G_2 G_3 G_4 + G_1 G_2 G_5}{1 + G_2 G_3 H_1 + G_1 G_2 G_5 H_2 + G_1 G_2 G_3 G_4 H_2}$$

Take off point after summing is represented by a single node. While take off point before a summing point is represented by two different nodes.

$$T = \frac{\sum_{i=1}^k P_i \Delta_i}{\Delta} \quad \text{Two forward paths}$$

$$P_1 = G_1 G_2 G_3 G_4 \quad , \quad P_2 = G_1 G_2 G_5$$

$$\Delta_1 = 1 - (0) = 1 \quad , \quad \Delta_2 = 1 - (0) = 0$$

$$L_1 = -G_2 G_3 H_1 \quad , \quad L_2 = -G_1 G_2 G_5 H_2 \quad , \quad L_3 = -G_1 G_2 G_3 G_4 H_2$$

$$\Delta = 1 - (L_1 + L_2 + L_3) + 0 = 1 + G_2 G_3 H_1 + G_1 G_2 G_5 H_2 + G_1 G_2 G_3 G_4 H_2$$

$$\frac{C}{R} = \frac{G_1 G_2 G_3 G_4 + G_1 G_2 G_5}{1 + G_2 G_3 H_1 + G_1 G_2 G_5 H_2 + G_1 G_2 G_3 G_4 H_2}$$

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Integrated Model of Distributed Systems Wiktor B. Daszczuk, 2019-03-16 In modern distributed systems such as the Internet of Things or cloud computing verifying their correctness is an essential aspect This requires modeling approaches that reflect the natural characteristics of such systems the locality of their components autonomy of their decisions and their asynchronous communication However most of the available verifiers are unrealistic because one or more of these features are not reflected Accordingly in this book we present an original formalism the Integrated Distributed Systems Model IMDS which defines a system as two sets states and messages and a relation of the actions between these sets The server view and

the traveling agent's view of the system provide communication duality while general temporal formulas for the IMDS allow automatic verification. The features that the model checks include partial deadlock and partial termination communication deadlock and resource deadlock. Automatic verification can support the rapid development of distributed systems. Further on the basis of the IMDS the Dedan tool for automatic verification of distributed systems has been developed.

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