

Engineering Mechanics

Your Ultimate Cheat Sheet

Statics

VECTOR
 $\vec{a} = a_x \hat{i} + a_y \hat{j}$
 $|\vec{a}| = \sqrt{a_x^2 + a_y^2}$
 $\vec{a} \cdot \vec{b} = a_x b_x + a_y b_y$
 $\vec{a} \times \vec{b} = (a_x \hat{i} + a_y \hat{j}) \times (b_x \hat{i} + b_y \hat{j}) = (a_y b_x - a_x b_y) \hat{k}$

TRIANGLE
 $a^2 = b^2 + c^2 - 2bc \cos A$
 $\sin A / a = \sin B / b = \sin C / c$
 $\frac{1}{a} \cot A + \frac{1}{b} \cot B = \frac{1}{c} \cot C$

QUADRILATERAL
 $\vec{r}_1 + \vec{r}_2 = \vec{r}_3 + \vec{r}_4$
 $\vec{r}_1 + \vec{r}_2 + \vec{r}_3 + \vec{r}_4 = 0$

VECTOR
 $\vec{a} \cdot \vec{a} = a^2$
 $\vec{a} \cdot \vec{b} = ab \cos \theta$
 $\vec{a} \times \vec{a} = 0$
 $\vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$

Dynamics

KINEMATICS

LINEAR	ANGULAR
$s = vt$	$\theta = \omega t$
$v = u + at$	$\omega = \omega_0 + \alpha t$
$v^2 = u^2 + 2as$	$\omega^2 = \omega_0^2 + 2\alpha\theta$
$s = ut + \frac{1}{2}at^2$	$\theta = \omega_0 t + \frac{1}{2}\alpha t^2$

PROJECTILE
 Horizontal velocity: $v_x = u \cos \theta$
 Vertical velocity: $v_y = u \sin \theta - gt$
 Time of flight: $T = \frac{2u \sin \theta}{g}$
 Range: $R = \frac{u^2 \sin 2\theta}{g}$
 Maximum height: $H = \frac{u^2 \sin^2 \theta}{2g}$

WORK AND ENERGY
 Work: $W = \vec{F} \cdot \vec{s}$
 Kinetic Energy: $E_k = \frac{1}{2}mv^2$
 Potential Energy: $E_p = mgh$
 Conservation of Energy: $E_{total} = E_{kinetic} + E_{potential}$

IMPULSION
 Impulse: $J = \int F dt = \Delta p$
 Conservation of Momentum: $m_1 u_1 + m_2 u_2 = m_1 v_1 + m_2 v_2$

ROTATION AND ANGULAR MOMENTUM
 Torque: $\tau = r \times F$
 Angular Momentum: $L = I\omega$
 Conservation of Angular Momentum: $L = \text{constant}$

COLLISIONS

Collision Type	Equation
Elastic	$v_1 - v_2 = v_2' - v_1'$
Inelastic	$v_1 = v_2 = v'$
Partially Elastic	$v_1 - v_2 = e(v_2' - v_1')$
Perfectly Inelastic	$v_1 = v_2 = v'$

Rigid Bodies

Shape	Centroid	Diagram
Rectangle	$\bar{x} = \frac{b}{2}, \bar{y} = \frac{h}{2}$	
Circle	$\bar{x} = 0, \bar{y} = 0$	
Triangle	$\bar{x} = \frac{b}{3}, \bar{y} = \frac{h}{3}$	
Semicircle	$\bar{x} = 0, \bar{y} = \frac{4r}{3\pi}$	
Quarter Circle	$\bar{x} = \frac{4r}{3\pi}, \bar{y} = \frac{4r}{3\pi}$	

Engineering Mechanics Reference S

Arturo Cuomo



Engineering Mechanics Reference S:

This book delves into Engineering Mechanics Reference S. Engineering Mechanics Reference S is a vital topic that must be grasped by everyone, from students and scholars to the general public. The book will furnish comprehensive and in-depth insights into Engineering Mechanics Reference S, encompassing both the fundamentals and more intricate discussions.

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- Chapter 1: Introduction to Engineering Mechanics Reference S
- Chapter 2: Essential Elements of Engineering Mechanics Reference S
- Chapter 3: Engineering Mechanics Reference S in Everyday Life
- Chapter 4: Engineering Mechanics Reference S in Specific Contexts
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