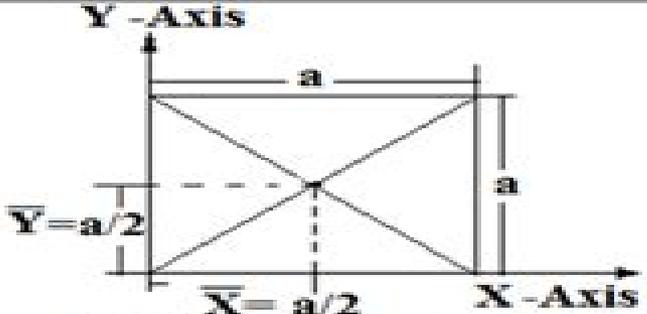
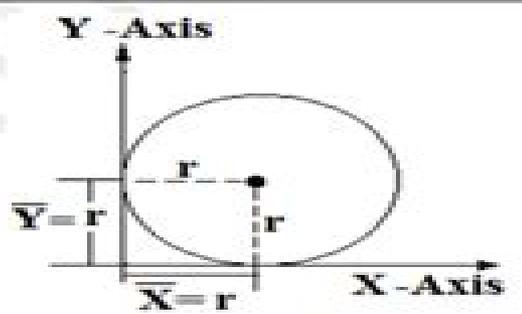
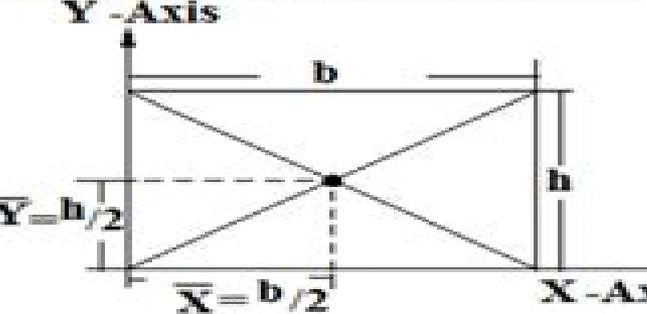
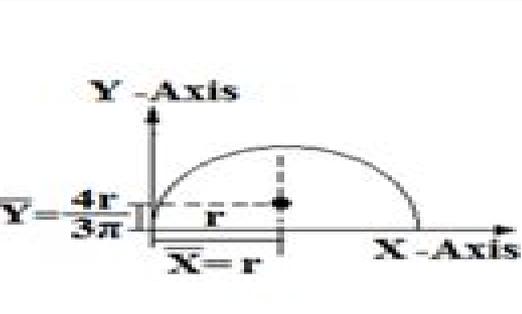
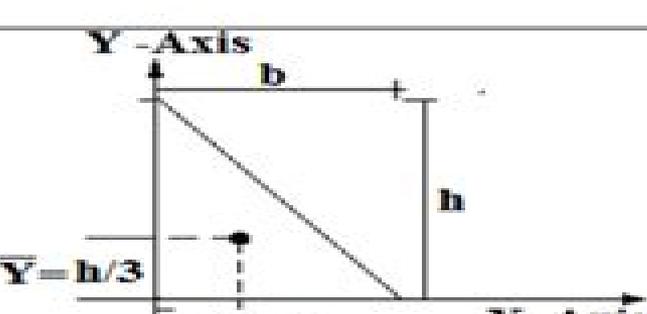
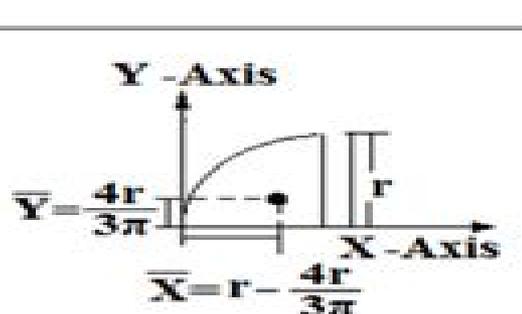
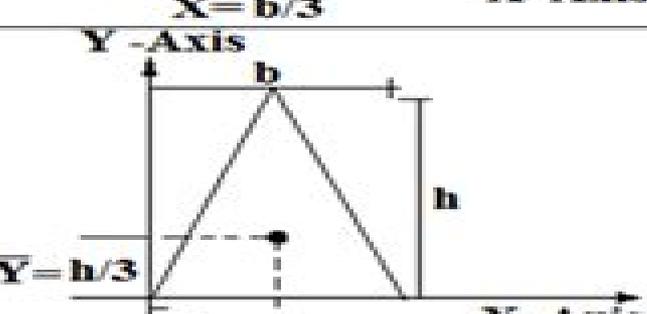
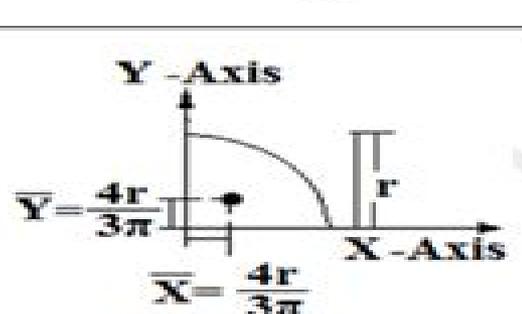


Centroid of basic geometrical figures

<p>Y - Axis</p>  <p>X - Axis</p>	<p>Square:</p> $\bar{X} = \frac{a}{2}$ $\bar{Y} = \frac{a}{2}$	<p>Y - Axis</p>  <p>X - Axis</p>	<p>Circle</p> $\bar{X} = r$ $\bar{Y} = r$
<p>Y - Axis</p>  <p>X - Axis</p>	<p>Rectangle</p> $\bar{X} = \frac{b}{2}$ $\bar{Y} = \frac{h}{2}$	<p>Y - Axis</p>  <p>X - Axis</p>	<p>Semi - Circle</p> $\bar{X} = r$ $\bar{Y} = \frac{4r}{3\pi}$
<p>Y - Axis</p>  <p>X - Axis</p>	<p>Right Angle Triangle</p> $\bar{X} = \frac{b}{3}$ $\bar{Y} = \frac{h}{3}$	<p>Y - Axis</p>  <p>X - Axis</p>	<p>Quarter - Circle</p> $\bar{X} = r - \frac{4r}{3\pi}$ $\bar{Y} = \frac{4r}{3\pi}$
<p>Y - Axis</p>  <p>X - Axis</p>	<p>Equilateral Triangle</p> $\bar{X} = \frac{b}{3}$ $\bar{Y} = \frac{h}{3}$	<p>Y - Axis</p>  <p>X - Axis</p>	<p>Quarter - Circle</p> $\bar{X} = \frac{4r}{3\pi}$ $\bar{Y} = \frac{4r}{3\pi}$

Engineering Mechanics Centroid Formulas

Julius Ludwig Weisbach



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