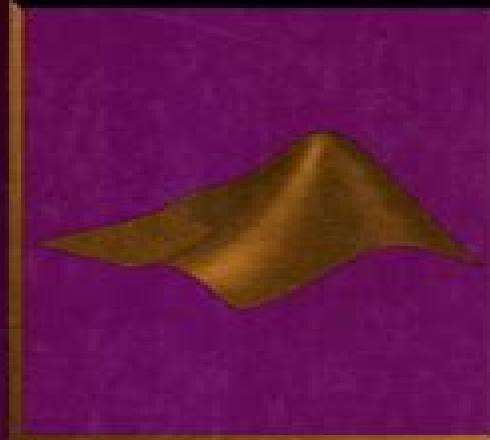


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**Companion MATLAB Guide to Linear Algebra** H. M. Edwards, 1996

**Control Systems Using MATLAB. Linear System Modeling** Levy P., 2016-11-21 In Control System Toolbox System Identification Toolbox and

Robust Control Toolbox software you represent linear systems as model objects Model objects are specialized data containers that encapsulate model data and other attributes in a structured way Model objects allow you to manipulate linear systems as single entities rather than keeping track of multiple data vectors matrices or cell arrays Model objects can represent single input single output SISO systems or multiple input multiple output MIMO systems You can represent both continuous and discrete time linear systems The main families of model objects are Numeric Models Basic representation of linear systems with fixed numerical coefficients This family also includes identified models that have coefficients estimated with System Identification Toolbox software Generalized Models Representations that combine numeric coefficients with tunable or uncertain coefficients Generalized models support tasks such as parameter studies or compensator tuning using Robust Control Toolbox tuning commands Model objects can represent individual components of a control architecture such as the plant actuators sensors or controllers You can connect model objects to build aggregate models of block diagrams that represent the combined response of multiple elements

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