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Reduced Order Output Feedback Control for Dynamic Systems Wai Chiu David Ng, 1979

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Feedback Stabilization of Controlled Dynamical Systems Nicolas Petit, 2017-03-24 This book is a tribute to Professor Laurent Praly and follows on from a workshop celebrating the occasion of his 60th birthday It presents new and unified visions of the numerous problems that Laurent Praly has worked on in his prolific career adaptive control output feedback and observers stability and stabilization His main contributions are the central topic of this book The book collects contributions written by prominent international experts in the control community addressing a rich variety of topics emerging ideas advanced applications and theoretical concepts Organized in three sections the first section covers the field of adaptive control where Laurent Praly started his career The second section focuses on stabilization and output feedback which is also the topic of the second half of his career Lastly the third section presents the emerging research that will form Laurent Praly's scientific legacy

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Feedback and Control for Everyone Pedro Albertos,Iven Mareels,2010-06-10 This intriguing and motivating book presents the basic ideas and understanding of control signals and systems for readers interested in engineering and science Through a series of examples the book explores both the theory and the practice of control

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Feedback Systems Karl Johan Åström,Richard Murray,2021-02-02 This book provides an introduction to the mathematics needed to model analyze and design feedback systems It is an ideal textbook for undergraduate and graduate students and is indispensable for researchers seeking a self contained reference on control theory Unlike most books on the subject Feedback Systems develops transfer functions through the exponential response of a system and is accessible across a range of disciplines that utilize feedback in physical biological information and economic systems Karl str m and Richard Murray use techniques from physics computer science

Independent Study in Feedback Control of Dynamic Systems Duane Peter Stevens,1999

Adaptive Feedback Control of Dynamic Systems Using Q-parameterization Mark Andrew McEver,2003

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