



Discrete Sliding Mode Control For Robust Tracking Of Time

JE Gale



Discrete Sliding Mode Control For Robust Tracking Of Time:

Sliding Mode Control Using Novel Sliding Surfaces B. Bandyopadhyay, Fulwani Deepak, Kyung-Soo Kim, 2009-09-23

After a survey paper by Utkin in the late 1970s sliding mode control methodologies emerged as an effective tool to tackle uncertainty and disturbances which are inevitable in most of the practical systems. Sliding mode control is a particular class of variable structure control which was introduced by Emel'yanov and his colleagues. The design paradigms of sliding mode control has now become a mature design technique for the design of robust controller of uncertain system. In sliding mode technique the state trajectory of the system is constrained on a chosen manifold or within some neighborhood thereof by an appropriate control action. This manifold is also called a switching surface or a sliding surface. During sliding mode system dynamics is governed by the chosen manifold which results in a well celebrated invariance property towards certain classes of disturbance and model mismatches. The purpose of this monograph is to give a different dimension to sliding surface design to achieve high performance of the system. Design of the switching surface is vital because the closed loop dynamics is governed by the parameters of the sliding surface. Therefore sliding surface should be designed to meet the closed loop specifications. Many systems demand high performance with robustness. To address this issue of achieving high performance with robustness we propose nonlinear surfaces for different classes of systems. The nonlinear surface is designed such that it changes the system's closed loop damping ratio from its initial low value to a final high value.

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Proceedings of the 2009 International Conference on Signals, Systems and Automation (ICSSA 2009) Himanshu Soni, 2010-04-30 This book is a collection of papers from the 2009 International Conference on Signals, Systems and Automation (ICSSA 2009). The conference at a glance: Pre-conference Workshops/Tutorials on 27th Dec 2009; Five Plenary talks; Paper/Poster Presentation 28-29 Dec 2009; Demonstrations by SKYVIEW Inc, SLS Inc, BSNL Baroda, Electric Meters, SIS. On-line paper submission facility on website. 200 papers are received from India and abroad. Delegates from different countries including Poland, Iran, USA. Delegates from 16 states of India. Conference website is seen by more than 3000 persons across the world, 27 countries and 120 cities. [The 8th International](#)

Conference on Robotic, Vision, Signal Processing & Power Applications Harsa Amylia Mat Sakim, Mohd Tafir Mustaffa, 2014-07-08 The proceeding is a collection of research papers presented at the 8th International Conference on Robotics Vision Signal Processing and Power Applications ROVISP 2013 by researchers scientists engineers academicians as well as industrial professionals from all around the globe The topics of interest are as follows but are not limited to Robotics Control Mechatronics and Automation Vision Image and Signal Processing Artificial Intelligence and Computer Applications Electronic Design and Applications Telecommunication Systems and Applications Power System and Industrial Applications

Advances in Neural Networks -- ISSN 2011 Derong Liu, Huaguang Zhang, Marios Polycarpou, Cesare Alippi, Haibo He, 2011-05-10 The three volume set LNCS 6675 6676 and 6677 constitutes the refereed proceedings of the 8th International Symposium on Neural Networks ISSN 2011 held in Guilin China in May June 2011 The total of 215 papers presented in all three volumes were carefully reviewed and selected from 651 submissions The contributions are structured in topical sections on computational neuroscience and cognitive science neurodynamics and complex systems stability and convergence analysis neural network models supervised learning and unsupervised learning kernel methods and support vector machines mixture models and clustering visual perception and pattern recognition motion tracking and object recognition natural scene analysis and speech recognition neuromorphic hardware fuzzy neural networks and robotics multi agent systems and adaptive dynamic programming reinforcement learning and decision making action and motor control adaptive and hybrid intelligent systems neuroinformatics and bioinformatics information retrieval data mining and knowledge discovery and natural language processing *Applied Mechanics Reviews*, 1998 Automation 2021: Recent Achievements in Automation, Robotics and Measurement Techniques Roman Szweczyk, Cezary Zieliński, Małgorzata Kaliczyńska, 2021-04-29 This book contains 38 papers authored by both scientists and practitioners focused on an interdisciplinary approach to the development of cyber physical systems Recently our civilization has been facing one of the most severe challenges in modern history The COVID 19 pandemic devastated the global economy and significantly disrupted numerous areas of economic activity Only radical increase of efficiency and versatility of industrial production with further limitation of human involvement paralleled by the decrease of environmental burden will enable us to cope with such challenges We hope that the presented book provides input to the solution of at least some problems brought about by this challenge This approach relies on the development of measuring techniques robotic and mechatronic systems industrial automation numerical modeling and simulation as well as application of artificial intelligence techniques required by the transformation leading to Industry 4.0

Proceedings of the ASME Dynamic Systems and Control Division, 2006

Robust Control Design 2003 Sergio Bittanti, Patrizio Colaneri, 2004 *Proceedings of the ... IEEE International Conference on Control Applications*, 1996 **Journal of Dynamic Systems, Measurement, and Control**, 2004 Publishes theoretical and applied original papers in dynamic systems Theoretical papers present new theoretical developments and

knowledge for controls of dynamical systems together with clear engineering motivation for the new theory Applied papers include modeling simulation and corroboration of theory with emphasis on demonstrated practicality 2002 IEEE Region 10 Conference on Computers, Communications, Control and Power Engineering TENCON (2002, Beijing), 2002 Robot Control 2000 (SYROCO'00) Peter Kopacek, 2001 IEE Proceedings Institution of Electrical Engineers, 1999 Indexes IEE proceedings parts A through I Conference Proceedings, 1997 Oceans '97 MTS/IEEE, 1997 This collection of papers covers applications of electrical and electronics equipment to oceanic environments The information regarding weather conditions design of vehicles to cope with oceans perception of remote conditions via technology and other topics will find increasing use in commerce Proceedings of the ... American Control Conference, 2005 International Aerospace Abstracts, 1999 Robust Control Via Variable Structure and Lyapunov Techniques Franco Garofalo, Luigi Glielmo, 1996 A large part of today's fervour on robust control research is focused on those techniques which utilise the Variable Structure Control Method and Lyapunov's Second Method and which constitute the backbone of the so called deterministic control of uncertain systems The chapters of this book cover a large spectrum of the recent research and introduce the most innovative ideas in the field Contained within the volume the reader will find a survey of control Lyapunov functions new structures of sliding mode controllers with discussion on higher order sliding modes new techniques for the design of direct and indirect adaptive controllers an introduction to the geometric theory of flat systems controllers for plants with component wise bounded inputs robust design via linear matrix inequalities and polytopic covering and some issues on the dissipativity and absolute stability of nonlinear systems **Proceedings, IEEE International Symposium on Intelligent Control**, 1996

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