

Multi-Body Simulation and Multi-Objective Optimization Applied to Vehicle Dynamics

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Abstract – This paper describes a demo application, where modeFRONTIER, a commercial software for design optimization, is coupled with a parametric 2D Multi-Body model of a touring motorcycle. The optimizer is asked to identify the characteristics of the front suspension (telelever scheme) that deliver more safety, more stability, and more riding comfort for a braking maneuver in straight running. All objectives are described through 4 scalar indexes, extracted from the braking kinematics.

As expected, results highlight that trade-off relationships connect the objectives. Only 13, among the 1900 tested configurations, are able to simultaneously improve the 4 indexes. Moreover, no design in this selection assures a decisive improvement of the stability. In order to accomplish this priority requirement, the best design is chosen accepting a slight reduction of stability.

Key words: Motorcycle Optimization, Braking Maneuver, Telelever, Multi-Objective Optimization, Design Optimization

1 Introduction

Dynamical performances of two wheeled vehicles largely depend on the response of each component. Among all components, tires and suspensions are the most important sub-systems, because their role is to modulate any force going from the road to the chassis [1, 2, 3, 4]. Therefore, a deep knowledge of such parts can be the turning key to develop better and safer motorcycles.

Multi-Body Simulation is the most suitable approach to perform vehicle dynamics investigation [5, 6, 7]. By creating parametric models, different configurations can be quickly evaluated, even at the earliest stage of the entire development process. From a business perspective, this means that wrong gateways can be dropped long before they lead to costly and useless real prototypes.

These benefits can be further increased by coupling the Multi-Body Simulation software with modeFRONTIER, which automatically plans and drives sets of simulations in order to perform complex tasks such as Design of Experiment, Parameter Sensitivity Analysis, and Multi-Objective Optimization.

This paper describes a demo application, where modeFRONTIER is asked to identify the parameters of a motorcycle front suspension to deliver more safety, more stability, and more riding comfort for a braking maneuver in straight running. Although the research is targeted to a very specific case, the proposed methodology can be straightforwardly extended to any user-defined running condition. Potentially, it is possible to build a single modeFRONTIER project to optimize different vehicle parts for various maneuvers.

As expected, results highlight that trade-off relationships connect the objectives, hence full optimization is almost impossible. Only 13, among the 1900 tested configurations, are able to simultaneously improve the 4 scalar indexes that have been previously defined to measure the objectives.

Moreover, no design in this selection promises a decisive improvement of the stability. In order to meet these primary requirements, the best design is chosen accepting a slight reduction of stability. The decision task has been totally supported by the Multi Criteria Decision Making tool implemented in modeFRONTIER.

2 The 2D Motorcycle Model

The Motorcycle is a complex multi-body system and special efforts are necessary to reliably simulate the overall dynamics. The broad range of literature available on this topic covers all simulation fields, such as time domain behavior [6, 7], optimal maneuver [8, 9], steady trim [10], frequency response [11], modal properties [5, 14, 15], tire dynamics [12], and so on. Since this research aims at highlighting the benefits of implementing an optimizer into the simulation chain, a detailed and validated model is not available. Model features have been implemented following state-of-art guidelines [13] to ensure sufficient result reliability.

As a simple test case, the vehicle behavior at braking during straight line motion is considered. In general, lateral dynamics plays an important role and a detailed 3D model would be recommended to perform thorough investigation. However, a 2D model includes enough features to study the influence of the front suspension on the braking distance, keeping the simulation complexity at reasonable level. Indirect considerations on stability and vehicle comfort can be made in any event by examining the variation of some in-plane quantities [4, 14].

The motorcycle model used in this research consists of 7 rigid bodies, such as chassis (which includes the rider), rear wheel, swinging arm, front wheel and three bodies for the front suspension with telelever scheme. Bodies are connected using proper joints to obtain the exact number of in-plane degrees of freedom.

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Multi-objective Evolutionary Optimisation for Product Design and Manufacturing Lihui Wang, Amos H. C. Ng, Kalyanmoy Deb, 2011-09-06 With the increasing complexity and dynamism in today's product design and manufacturing more optimal robust and practical approaches and systems are needed to support product design and manufacturing activities Multi objective Evolutionary Optimisation for Product Design and Manufacturing presents a focused collection of quality chapters on state of the art research efforts in multi objective evolutionary optimisation as well as their practical applications to integrated product design and manufacturing Multi objective Evolutionary Optimisation for Product Design and Manufacturing consists of two major sections The first presents a broad based review of the key areas of research in multi objective evolutionary optimisation The second gives in depth treatments of selected methodologies and systems in intelligent design and integrated manufacturing Recent developments and innovations in multi objective evolutionary optimisation make Multi objective Evolutionary Optimisation for Product Design and Manufacturing a useful text for a broad readership from academic researchers to practicing engineers

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7th International Munich Chassis Symposium 2016 Prof. Dr. Peter E. Pfeffer, 2016-08-15 In chassis development the three aspects of safety vehicle dynamics and ride comfort are at the top of the list of challenges to be faced Addressing this triad of challenges becomes even more complex when the chassis is required to interact with assistance systems and other systems for fully automated driving What is more new demands are created by the introduction of modern electric and electronic architectures All these requirements must be met by the chassis together with its subsystems the steering brakes tires and wheels At the same time all physical relationships and interactions have to be taken into account

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Conference on Maintenance Engineering and the 2021 conference of the Efficiency and Performance Engineering Network IncoME VI TEPEN 2021 held in Tianjin China on October 20-23 2021 Topics include vibro acoustics monitoring condition based maintenance sensing and instrumentation machine health monitoring maintenance auditing and organization non destructive testing reliability asset management condition monitoring life cycle cost optimisation prognostics and health management maintenance performance measurement manufacturing process monitoring and robot based monitoring and diagnostics The contributions which were selected through a rigorous international peer review process share exciting ideas that will spur novel research directions and foster new multidisciplinary collaborations *Fuzzy Systems and Data Mining V* Antonio J. Tallón-Ballesteros, 2019-11-15 The Fuzzy Systems and Data Mining FSDM conference is an annual event encompassing four main themes fuzzy theory algorithms and systems which includes topics like stability foundations and control fuzzy application which covers different kinds of processing as well as hardware and architectures for big data and time series and has wide applicability the interdisciplinary field of fuzzy logic and data mining encompassing applications in electrical industrial chemical and engineering fields as well as management and environmental issues and data mining outlining new approaches to big data massive data scalable parallel and distributed algorithms The annual conference provides a platform for knowledge exchange between international experts researchers academics and delegates from industry This book includes the papers accepted and presented at the 5th International Conference on Fuzzy Systems and Data Mining FSDM 2019 held in Kitakyushu Japan on 18-21 October 2019 This year FSDM received 442 submissions All papers were carefully reviewed by program committee members taking account of the quality novelty soundness breadth and depth of the research topics falling within the scope of FSDM The committee finally decided to accept 137 papers which represents an acceptance rate of about 30% The papers presented here are arranged in two sections Fuzzy Sets and Data Mining and Communications and Networks Providing an overview of the most recent scientific and technological advances in the fields of fuzzy systems and data mining the book will be of interest to all those working in these fields **Airdrop Recovery Systems With Self-Inflating Airbag** Hongyan Wang, Qiang Rui, Huangjie Hong, Jianyang Li, 2017-06-13 A complete reference text to airdrop recovery systems with self inflating airbags focusing on analysis test data and engineering practicalities Comprehensively covers the fundamental theories design matching and analysis of airdrop recovery systems that include a parachute and self inflating airbag system Gives step by step guidance to aid readers in analyzing and designing their own recovery systems Highlights advanced research programs in the field of airdrop recovery systems such as simulation and optimization methods **Proceedings of the ASME Design Engineering Division**, 2007 **Proceedings of the International Symposium on Advanced Vehicle Control 1994**, 1994 **International Aerospace Abstracts**, 1999 **Large Space Structures & Systems in the Space Station Era**, 1991 **Large Space Structures and Systems in the Space Station Era: A Bibliography with Indexes (supplement 04)**, 1992 NASA

Conference Publication ,1991 Proceedings of the ASME International Design Engineering Technical Conferences and Computers and Information in Engineering Conferences--2005 ,2005 **Proceedings of the 8th Biennial Conference on Engineering Systems Design and Analysis--2006: Dynamic systems and controls. Symposium on design and analysis of advanced structures. Tribology** ,2006 **Sheet Metal 2009** B. Shirvani,2009 Dissertation Abstracts International ,2008 *Proceedings of the Tenth International Conference on Civil, Structural and Environmental Engineering Computing* B. H. V. Topping,2005 Contains the abstracts of the contributed papers presented at the Tenth International Conference on Civil Structural and Environmental Engineering Computing held in Rome Italy 30 August 2 September 2005 The length papers are available in electronic format on the accompanying CD ROM *The Engineering Index Annual* ,1992 Since its creation in 1884 Engineering Index has covered virtually every major engineering innovation from around the world It serves as the historical record of virtually every major engineering innovation of the 20th century Recent content is a vital resource for current awareness new production information technological forecasting and competitive intelligence The world s most comprehensive interdisciplinary engineering database Engineering Index contains over 10 7 million records Each year over 500 000 new abstracts are added from over 5 000 scholarly journals trade magazines and conference proceedings Coverage spans over 175 engineering disciplines from over 80 countries Updated weekly **Water Resources Systems--hydrological Risk, Management and Development** Günter Blöschl,2003 **Proceedings, IEEE Control Systems Society ... Symposium on Computer-Aided Control System Design (CACSD)**. ,1999

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as well as when it is not the diode carries the current during the off period of the transistor therefore energy flows into the load during both the periods

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web the figure given below represents the functional block diagram of smps initially the unregulated ac input signal from the source is provided to the input rectifier and filter circuit here the ac input signal is rectified to generate a dc signal and further smoothed to remove high frequency noise component from it

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