

ENGINEERING PHD RESEARCH PROPOSAL SAMPLE

SOFTWARE ENGINEERING ROLE IN THE WORKPLACE LEARNING PROCESS

In today's rapidly changing world, it is imperative to constantly increase the level of knowledge in order to keep up with new challenges. Some individuals who were considered educated in the past can today become unsuitable to respond to current and future demands of the environment. The fact is that learning is done in the workplace. It is necessary for the development of knowledge and skills that are necessary for the employees to progress, but also to achieve the company's competitiveness. Workplace learning includes a range of activities that employees need to take to master new skills needed to better perform their jobs. Examples of such activities are: searching for adequate resources relevant to the tasks, learning materials, applying new learning activities in collaboration with other colleagues, learners, and relevant experts. In the world of change, learning at the workplace is defined as an enterprise worth millions of dollars where employees learn new skills designed to help maintain the organization's competitiveness in a rising global economic environment (Sachanand, 2000). In the past few years, among employees, researchers and business policy makers, there has been an interest in increasing and facilitating workplace learning. Today there are many areas of research where the central interest is learning for time and at work. The concept of the "learning organization" is another example where the focus is set, although other concepts such as "lifelong learning" and "learning community" define the areas of research that contribute to the development of workplace learning as a separate field of research (Lee et al, 2008). Creating a learning climate and innovation within the organization provides incentives to acquire new experiences in the workforce, which leads to a change in traditional tasks and the elimination of boundaries at work itself (Rice, & Rice, 2008). These activities reflect on the activities undertaken at the workplace

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Chao Zhang



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Handbook of Research on Emerging Trends and Technologies in Library and Information Science Kaushik, Anna, Kumar, Ashok, Biswas, Payel, 2019-11-22 With the perpetual advancements of technology library and information science professionals are tasked with understanding these technologies and providing accurate and comprehensive information to other potential users These professionals must develop best practices for understanding these technologies in order to best serve other users The Handbook of Research on Emerging Trends and Technologies in Library and Information Science is a critical research book that examines advancing technologies and new innovations and their influences on library and information sciences for improved best practices Featuring an array of topics such as digital libraries distance education and information literacy this publication is essential for librarians knowledge managers information retrieval specialists library and information science professionals information scientists researchers web librarians academicians educators IT specialists and managers [Hispanic Engineer & IT](#) ,2000-02 Hispanic Engineer Information Technology is a publication devoted to science and technology and to promoting opportunities in those fields for Hispanic Americans [U.S. Government Research & Development Reports](#) ,1965 [Pneumatic Servo Systems Analysis](#) Ling Zhao, Yuanqing Xia, Hongjiu Yang, Jinhui Zhang, 2022-02-10 This book focuses on pneumatic servo systems analysis control and application in robotic systems The pneumatic servo systems are composed by pneumatic artificial muscles or cylinders which are two important pneumatic actuators in industrial application The active disturbance rejection control technique is used effectively to solve strong nonlinearity and uncertain factors for the pneumatic servo systems Nonlinear feedback control back stepping control finite time control sliding mode control and several other control laws are proposed to make the pneumatic servo systems have better control performances The book establishes a fundamental framework for this topic while emphasizing the importance of integrated analysis The book is intended for undergraduate and graduate students who are interested in this field and engineers working on the applications of pneumatic servo systems [Advances in Industrial Control reports and encourages the transfer of technology in control engineering](#) The rapid development of control technology has an impact on all areas of the control discipline The series offers an opportunity for researchers to present an extended exposition of new work in all aspects of industrial control **Electrical Engineering** ,1958 [Image-Based and Fractional-Order Control for Mechatronic Systems](#) Cosmin Copot, Clara Mihaela Ionescu, Cristina I. Muresan, 2020-04-10 This book unites two fast developing forms of control vision based control and fractional order control and applies them in mechatronic systems Image Based and Fractional Order Control for Mechatronic Systems is presented in two parts covering the theory and applications of the subject matter The theoretical material presents the concepts of visual servoing and image based feature extraction for feedback loops and fractional order control It discusses a range of systems from the classic monocular camera to new RGB D sensors The applications part of the book first discusses practical issues with the implementation of fractional order control

comparing them with more traditional integer order PID systems The authors then introduce real life examples such as a manipulator robot and a Stewart platform and results generated from such systems MATLAB functions and source codes are included wherever relevant to help readers develop simulations based on the theoretical ideas and practical examples in the text Suggestions for the use of other pertinent open source software are also indicated with the places where such may be obtained With its combination of theoretical ideas and practical examples Image Based and Fractional Order Control for Mechatronic Systems will be of interest to academic researchers looking to develop the fields of vision based and fractional order control and to engineers who are looking for developments that will help them provide closer control of their plants than can be achieved with integer order PID Advances in Industrial Control reports and encourages the transfer of technology in control engineering The rapid development of control technology has an impact on all areas of the control discipline The series offers an opportunity for researchers to present an extended exposition of new work in all aspects of industrial control

Robust Integration of Model-Based Fault Estimation and Fault-Tolerant Control Jianglin Lan, Ronald J. Patton, 2020-12-11 Robust Integration of Model Based Fault Estimation and Fault Tolerant Control is a systematic examination of methods used to overcome the inevitable system uncertainties arising when a fault estimation FE function and a fault tolerant controller interact as they are employed together to compensate for system faults and maintain robustly acceptable system performance It covers the important subject of robust integration of FE and FTC with the aim of guaranteeing closed loop stability The reader's understanding of the theory is supported by the extensive use of tutorial examples including some MATLAB based material available from the Springer website and by industrial applications based material The text is structured into three parts Part I examines the basic concepts of FE and FTC providing extensive insight into the importance of and challenges involved in their integration Part II describes five effective strategies for the integration of FE and FTC sequential iterative simultaneous adaptive decoupling and robust decoupling and Part III begins to extend the proposed strategies to nonlinear and large scale systems and covers their application in the fields of renewable energy robotics and networked systems The strategies presented are applicable to a broad range of control problems because in the absence of faults the FE based FTC naturally reverts to conventional observer based control The book is a useful resource for researchers and engineers working in the area of fault tolerant control systems and supplementary material for a graduate or postgraduate level course on fault diagnosis and FTC Advances in Industrial Control reports and encourages the transfer of technology in control engineering The rapid development of control technology has an impact on all areas of the control discipline The series offers an opportunity for researchers to present an extended exposition of new work in all aspects of industrial control

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